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Abstract	<p>The reduced Lippmann-Schwinger-Lanczos (LSL) algorithm, initially designed for two-dimensional (2D) inverse problems within the diffusion domain in the context of reduced-order modeling (ROM) (Baker et al., Regularized reduced order Lippmann-Schwinger-Lanczos method for inverse scattering problems in the frequency domain (submitted). arXiv:2311.16367v1) and later adapted to one-dimensional (1D) inverse scattering in the wave domain (Abilgazy and Zaslavsky, Lippmann-Schwinger-Lanczos approach for inverse scattering problem of Schrödinger equation in the resonance frequency domain. Extended abstracts of IPMS 2024 conference (accepted)), is extended in this work to address 2D Schrödinger inverse problems. Numerical experiments demonstrate that the required frequency sampling rate for 2D wave problems is substantially lower than for the 1D case, attributed to the inherently overdetermined nature of the 2D inverse problem. This finding suggests potential efficiency gains for solving high-dimensional wave-based inverse problems using reduced sampling strategies.</p>
Keywords (separated by “ - ”)	Lippmann-Schwinger equation - Lanczos - Reduced order model
MSC 2020 (separated by “ - ”)	35R30 - 47A52 - 65N21 - 65F22 - 78A46

Chapter 321

Reduced Order2

Lippmann-Schwinger-Lanczos Inverse3

Scattering Method4

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The inverse scattering problem formulated for the Helmholtz and Schrödinger operators has wide-reaching applications in fields such as quantum mechanics, remote sensing, geophysical, and medical imaging. Efficient numerical methods for inverse scattering have been developed in application to acoustic imaging, electromagnetic sensing, seismic exploration, and other fields. These methods include iterative techniques based on adjoint or backpropagation methods, Born and Rytov approximations, layer stripping methods, asymptotic methods for small volume inhomogeneities, Kirchhoff migration, and solving the Lippmann-Schwinger (LS) integral equation, see [7, 12, 14], also see a more recent review [13] and references therein discussing, in addition to the above mentioned techniques, far field and near field methods as well as phaseless recovery and nonlinear approaches. The problem is known to be severely ill-posed [6, 11].

Here, we use a truncated Lanczos representation to compute the data-driven internal solution of the PDE with unknown coefficients and then substitute it into the LS problem, thus effectively making it linear, as proposed in [9]; this results in the Lippmann-Schwinger-Lanczos (LSL) algorithm. The stability of projection subspaces in reduced order models (ROMs) is a critical concern, particularly when dealing with ill-posed problems. The sensitivity to data errors and potential nonphysical indefiniteness of the mass and stiffness matrices can lead to the loss of the Hamiltonian property in the reduced order system. To address this issue, two level ROM regularization via Gramian truncation is introduced in [3] to stabilize the LS algorithm. for the solution of the 2D inverse problem in the diffusion regime. The problem considered in [3] used a multiple-input multiple-output (MIMO) formulation corresponding to a symmetry preserving discretization of the 2D Neumann-to-Dirichlet (NtD) map. The LSL algorithm was extended to the wave domain for 1D inverse scattering problems [1] in single-input single-output (SISO) formulation, corresponding to the data given as a frequency-dependent 1D NtD a.k.a. scalar Weyl or transfer function. Here we apply the LSL algorithm to a 2D inverse problem in MIMO formulation for Schrödinger equation in the wave domain, which is a commonly used model in inverse scattering.

We note that the extension to a more general class of inverse problems may be possible with additional iterations [5], however, introducing iterations would compromise the advantages provided by direct inversion methods.

The LSL Method We consider the Schrödinger equation in a bounded domain Ω in \mathbb{R}^d , $d > 1$, with a smooth boundary $\partial\Omega$ at the wavenumber squared λ ,

$$\Delta u(x) + p(x)u(x) + \lambda u(x) = 0 \text{ in } \Omega, \quad \frac{\partial u}{\partial n} = g \text{ on } \partial\Omega. \quad (32.1)$$

The inverse scattering problem seeks identifying the nonnegative potential $p(x)$ using measured multifrequency Dirichlet data at a single or multiple receivers along the boundary, corresponding to a partial NtD map given by Neumann condition g .

Notice that we can rewrite the inhomogeneous Neumann boundary condition as the source $g(x)$ in the domain, assuming $g(x)$ is a compactly supported real

distribution localized near the boundary. A complete set of such distributions will define the NtD operator, which is a tensor of order $2d - 2$ for every λ . Thus, the inverse problem of determining $p(x)$ from the NtD given for a frequency interval becomes overdetermined for $d > 1$. Denoting the operator in (32.1) as \mathcal{L} , we (formally) represent the solution using the resolvent operator as

$$u = (\mathcal{L} + \lambda I)^{-1} g, \quad \text{where} \quad \mathcal{L} = -\Delta + pI \quad (32.2)$$

defined for functions on Ω satisfying the homogeneous Neumann boundary condition at $\partial\Omega$. The LSL method uses the values of the transfer function $F(\lambda)$ as the data:

$$F(\lambda) = \langle g, u \rangle = \int_{\partial\Omega} g(x)u(x, \lambda)dx = \langle g, (-\Delta + pI + \lambda I)^{-1} g \rangle \quad (32.3)$$

The case with $d = 1$ considered in [1] corresponds to the Schrödinger equation for a scalar function u in the domain $\Omega = (0, L)$, $0 < L < \infty$. The data for the inversion are the values of the function $F(\lambda)$ and its derivative given for specific $\lambda_j \in \mathbb{R}$, $j = 1, \dots, m$:

$$F(\lambda)|_{\lambda=\lambda_j} \in \mathbb{R}, \quad \frac{dF(\lambda)}{d\lambda}|_{\lambda=\lambda_j} \in \mathbb{R} \quad \text{for } j = 1, \dots, m. \quad (32.4)$$

The SISO inverse problem requires to determine $p(x)$ in (32.1) from the data (32.4) with real or complex-valued function $F(\lambda)$ and correspond collocated receiver and transmitter density $g(x)$ as given by (32.3). The MIMO formulation with l collocated transmitter and receiver distributions g_i normally used for $d > 1$ and usually corresponds to symmetrix matrix valued function $F(\lambda) \in \mathbb{C}^{l \times l}$ with elements

$$F_{ij}(\lambda) = \langle g_i, (-\Delta + pI + \lambda I)^{-1} g_j \rangle, \quad i = 1, \dots, l, \quad j = 1, \dots, l.$$

Normally g_i are chosen in such way, that $F(\lambda)$ becomes an approximation of the NtD map.

In [3], the authors considered diffusion formulation with data on an interval of \mathbb{R}_+ . Here we consider a wave formulation on the real negative interval $\lambda \in [\lambda_{min}, 0] \subset \mathbb{R}_-$. The diffusion case corresponds to the Laplace transform of the diffusion equation with exponential factor $e^{-\lambda t}$ with $\lambda > 0$. Our formulation in the wave domain arises from the Fourier transform of the wave equation with the time-dependent harmonic factor $e^{\pm i\omega}$, where ω is the harmonic frequency of the oscillation yielding $\lambda = -\omega^2$. Shifting from positive to negative intervals of λ in wave problems produces images of significantly higher resolution, however it requires different sampling strategies.

A positive interval lays outside of the spectrum of \mathcal{L} , and the choice of the data points can be based, for example, on H_2 optimal points [4]. However, a large

enough negative interval contain the spectrum, so to accurately describe the transfer function, the data points should separate the spectral points, i.e., at least alternate with the spectral points. Density of spectral points can be estimated via Weyl's law

$$\lim_{\lambda \rightarrow \infty} \frac{N(\lambda)}{\lambda^{d/2}} = (2\pi)^{-d} \omega_d \text{vol}(\Omega), \quad (32.5)$$

where ω_d is the volume of the unit ball in \mathbb{R}^d . Here $N(\lambda)$ is the number of the eigenvalues less than or equal to λ . Generally, we choose density of sample points as $c \frac{d}{d\lambda} N(\lambda)$ with a moderate integer oversampling constant $c > 1$, that for $d > 1$ yields good results. To avoid overflow, we remove data points with absolute measurement values above certain threshold, that lay to close to the spectral points. We also note that inverse scattering problem in multi-dimensional case $d > 1$ is over-determined for MIMO scenario, so it is enough to use $c = 2$. In contrast, for 1D SISO problem values $c \geq 3$ are required for good reconstructions [1].

Lippmann-Schwinger Integral Equation If F_0 is the background transfer function corresponding to the solution u^0 for known p_0 , then the nonlinear Lippmann-Schwinger equation for the unknown function p can be written as

$$F_0 - F = \langle u^0, pu \rangle \quad (32.6)$$

where u is the (unknown) solution corresponding to the (unknown) coefficient p . One of the main difficulties of applying the LS approach to inverse problems is that this is a nonlinear equation. The LSL method [9] uses a (data-driven) approximate \tilde{u} of the solution u which is computed via Lanczos orthogonalization directly from the data without knowing p . This leads to the linear with respect to p equation: $F_0 - F \approx \langle u^0, p\tilde{u} \rangle$. This precomputing is based on embedding properties of the data-driven reduced order models (ROMs) developed in [8] and results in the linear system of equations for $p(x)$:

$$F_0(\lambda_j) - F(\lambda_j) = \int_{\partial\Omega} u_0(x, \lambda_j) \tilde{u}(x, \lambda_j) p(x) dx, \quad j = 1, \dots, m \quad (32.7)$$

LSL Algorithm A critical component of the LSL algorithm is computation of \tilde{u} , so we address it in more details. Let $u_j = u(x, \lambda_j)$ be solutions to (32.1) corresponding to $\lambda = \lambda_j$ for $j = 1, \dots, m$. We construct the Galerkin system that determines the data-driven Reduced Order Model (ROM) by projecting the problem (32.1) into the subspace V spanned by the functions $u_1(x), \dots, u_m(x)$,

$$(S + \lambda M)c = b. \quad (32.8)$$

Here the symmetric, positive definite stiffness and mass $m \times m$ block matrices respectively \mathbf{S} and \mathbf{M} with $l \times l$ blocks obtained from the data via Loewner algorithm [3–5, 10]:

$$M_{ij} = \frac{F(\lambda_i) - F(\lambda_j)}{\lambda_j - \lambda_i}, \quad M_{ii} = -\frac{dF}{d\lambda}(\lambda_i). \quad (32.9)$$

and

$$S_{ij} = \frac{F(\lambda_j)\lambda_j - F(\lambda_i)\lambda_i}{\lambda_j - \lambda_i}, \quad S_{ii} = \frac{d(\lambda F)}{d\lambda}(\lambda_i). \quad (32.10)$$

The right-hand side \mathbf{b} is a real vector of $l \times l$ blocks given by $F(\lambda_j)$. For any λ , the solution to (32.1) can be approximated by data-generated solution

$$u \approx \tilde{u} = V\mathbf{c} = V(\mathbf{S} + \lambda\mathbf{M})^{-1}\mathbf{b}, \quad (32.11)$$

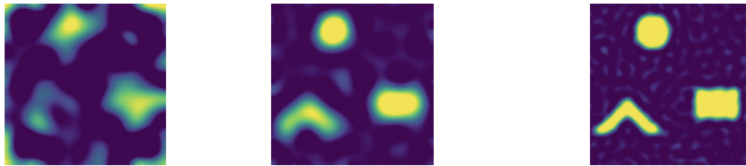
where V is an operator that can be represented via semi-infinite matrix $V \in \mathbb{R}^{\infty \times ml}$ with vector-columns from a Hilbert space given by orthogonalized background snapshots computed for $p \equiv 0$ at λ_i , $i = 1, \dots, m$. A key component of the data-driven ROM approach is asymptotic independence of the orthogonalized snapshots V on unknown $p(x)$, in spite of possibly strong dependence of the original snapshots u . This is thanks to the specially chosen orthogonalization algorithm via the block-Lanczos recursion with matrix $\mathbf{M}^{-1}\mathbf{S}$ and initial block-vector \mathbf{b} [5, 9]. Thus, all the parameters in the r.h.s. of (32.11) can be computed from the data, so we call \tilde{u} data-driven or data-generated solution.

To summarize, the LSL algorithm executes the following steps. The first step is constructing the data generated internal solution \tilde{u} via (32.11). The next step is to solve the linear system of Lippmann-Schwinger integral equations (a linear inverse problem). Indeed, use of $\tilde{u}(x, \lambda_j)$ instead of $u(x, \lambda_j)$ in the Lippmann-Schwinger integral equation produces a linear system for the unknown $p(x)$ given by (32.7).

The disadvantage of the LSL method is that improving the quality of the reconstructed solution requires increasing the number of frequencies. However, as the number of frequencies increases, the condition number of Loewner matrices \mathbf{S} and \mathbf{M} increases, and due to noisy data they can lose their positive-definiteness, leading to breakdown of the orthogonalization algorithm. To prevent this, a regularized (truncated) Reduced Order Model is constructed in [3] by projecting matrix pencil (\mathbf{S}, \mathbf{M}) onto the eigenvectors of \mathbf{M} corresponding to the real positive eigenvalues. Additional regularization is implemented to address intrinsic ill-posedness of

The regularized LSL algorithm provides an efficient approximation of the resolvent and results in a stable numerical algorithm.

Results of Numerical Simulations for the MIMO Problem Here, we present 2D results of numerical reconstructions of the perturbation composed of three shapes: a circle, a rectangle and a corner, embedded in homogeneous background $p_0 = 0$



Born for $\lambda \in [-80; -2]$ Reconstruction for $\lambda \in [-80; -2]$ Reconstruction for $\lambda \in [-380; -2]$

Fig. 32.1 Shape perturbation reconstruction using the Born, and LSL methods

in $\Omega = [-1; 1]^2$. All three objects have the intensity $p = 1$. We considered MIMO dataset with 8 collocated sources/receivers located on the boundary $\partial\Omega$ (2 per each piece of boundary) and multiple frequencies. In Fig. 32.1 we plotted the results of reconstructions for frequency range $\lambda \in [-80; -2]$ obtained by Born (left) and LSL (middle) as well as by LSL for $\lambda \in [-380; -2]$. As one can observe, our approach strongly overperforms Born for the same dataset. Also, adding higher frequencies allowed to sharpen the image significantly. We also note that these reconstructions are much sharper than the ones obtained in [3] for diffusion Schrödinger problem.

Conclusions The paper discusses the data-driven reduced Lippman-Schwinger-Lanczos (LSL) method providing an efficient approach to inverse scattering for multi-dimensional Schrödinger problem in a wave regime. The LSL is the direct reconstruction algorithm that gives an explicit map between the ROM and the unknown potential p ; it does not require an iterative numerical scheme. Other advantages of the method are stability of the regularized ROM and construction of the Galerkin ROM, exactly matching the data, directly from the data. Employing the wave formulation allowed to sharpen the images compared to diffusion Schrödinger problem [3]. We observed that the sampling rate can be significantly relaxed compared to the 1D case [1]. We can speculate that such relaxation is possible thanks to the overdetermined nature of the 2D formulation using frequency-dependent NtD map, and probably even more sampling coarsening is expected for 3D problems.

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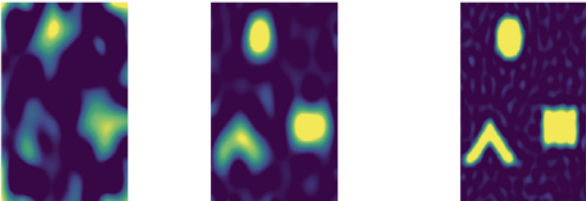
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Page no	Fig/Photo	Thumbnail	Alt-text Description
	Fig1	<div><p>Born for $\lambda \in [-80; -2]$ Reconstruction for $\lambda \in [-80; -2]$ Reconstruction for $\lambda \in [-380; -2]$</p></div>	<p>Three abstract images are displayed side by side. The first image, labeled "Born for $\lambda \in [-80; -2]$," shows a pattern of blurred, colorful shapes. The second image, labeled "Reconstruction for $\lambda \in [-80; -2]$," features similar shapes with slightly more defined edges. The third image, labeled "Reconstruction for $\lambda \in [-380; -2]$," presents distinct geometric shapes, including a circle, triangle, and rectangle, with clear boundaries. The color scheme includes shades of purple, blue, and yellow.</p>