



Follow the Mass—A Concordance Picture of Tidal Disruption Events

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Abstract

Three recent global simulations of tidal disruption events (TDEs) have produced, using different numerical techniques and parameters, very similar pictures of their dynamics. In typical TDEs, after the star is disrupted by a supermassive black hole, the bound portion of the stellar debris follows highly eccentric trajectories, reaching apocenters of several thousand gravitational radii. Only a very small fraction is captured upon returning to the vicinity of the supermassive black hole. Nearly all of the debris returns to the apocenter, where shocks produce a thick irregular cloud on this radial scale and power the optical/UV flare. These simulation results imply that over a few years, the thick cloud settles into an accretion flow responsible for the long-term emission. Despite not being designed to match observations, and without any free parameters, the dynamical picture given by the three simulations aligns well with observations of typical events, correctly predicting the flares' typical total radiated energy, luminosity, temperature, and emission-line width. On the basis of these predictions, we provide an updated method (TDEMASS) to infer the stellar and black hole masses from a flare's peak luminosity and temperature. This picture also correctly predicts that the luminosity observed years after the flare should be nearly constant. In addition, we show that in a magnitude-limited survey, if the intrinsic rate of TDEs is independent of black hole mass, the detected events will preferentially have black hole masses $\sim 10^{6.3 \pm 0.3} M_{\odot}$ and stellar masses $\sim 1 M_{\odot}$.

Unified Astronomy Thesaurus concepts: Tidal disruption (1696); Ultraviolet transient sources (1854); X-ray transient sources (1852)

1. Introduction

Tidal disruption events (TDEs) are inherently dramatic: a star is ripped apart by the gravity of a supermassive black hole. The result is a flare in which, for a month or two, the former star radiates with $\sim 10^{10} \times$ its ordinary luminosity. Over the duration of the flare (typically months), TDEs are among the most luminous transients known. Once hard to find, there are now ~ 100 known examples (N. Kaiser et al. 2002; B. J. Shappee et al. 2014; M. R. Blanton et al. 2017; E. C. Bellm et al. 2019; E. Hammerstein et al. 2023a), and many more can be expected from new instruments (e.g., the Rubin Observatory, K. Brincman & A. Gomboc 2020; K. Szekerczes et al. 2024; and ULTRASAT, S. Ben-Ami et al. 2022) due to go online soon.

As TDEs involve infall of matter onto a black hole, they are of significant interest as a tool to explore dynamical accretion processes. They also have potential interest as a probe of the black hole population in galactic nuclei and the dynamical relationship between those nuclear black holes and the surrounding stars.

In addition to these reasons, they also merit attention as truly multiwavelength systems (see T. Wevers & T. Ryu 2023, for the most recent review). TDEs have been observed mostly in the optical, but at times, they shine in X-rays and in radio as well. The emission in different bands typically comes at different times and emerges from different locations, indicating that multiple mechanisms contribute to their radiation processes.

To identify where and how the radiation is emitted, the first task is to track where the debris mass goes. When the star's

orbit is effectively parabolic and the star has been fully disrupted, half the star's mass is unbound and escapes to infinity, while the other half remains bound to the black hole (M. J. Rees 1988). Although there is a firm consensus that the bound mass is initially placed on highly eccentric orbits whose apocenters are thousands of gravitational radii, $\sim O(10^2) \times$ the stellar pericenter, hitherto there has been little agreement about its whereabouts following its first return to the pericenter. The oldest, and still most prevalent, view has been that the bound material immediately forms a compact accretion disk on the pericenter scale (M. J. Rees 1988). This picture predicts a very luminous X-ray source, but the observed spectra have luminosities $\sim 10^{-2} \times$ this prediction, and shapes well fit by blackbodies with temperatures $\gtrsim 10^4$ K and radiating areas corresponding to the apocenter scale (see S. van Velzen et al. 2020; E. Hammerstein et al. 2023a, for two recent data compilations). To explain these unexpected observations, many (e.g., L. E. Strubbe & E. Quataert 2009, 2011; B. D. Metzger & N. C. Stone 2016) have suggested that the X-rays are reprocessed by different material associated with the event whose photosphere happens to be at this distance from the black hole. Alternatively, it has also been suggested (H. Shiohara et al. 2015) that, rather than forming a compact disk, the bound material returns to the apocenter region and, upon colliding with later-returning bound debris, forms a large irregular cloud on a scale similar to the apocenter distance. In this picture (T. Piran et al. 2015), the shocks associated with these collisions power the flare.

The question of where the debris finds itself shortly after the disruption is given further importance by the fact that the energy available for radiation is exactly the binding energy of the debris orbits. The binding energy per unit mass is, of course, inversely proportional to the semimajor axis of a given fluid element's orbit. Given the large discrepancy between the

ratio of radiated energy to debris mass and the energy per unit mass released in relativistic accretion, the orbital distribution is, therefore, of prime dynamical interest.

Large-scale numerical simulations treating most of the bound debris have the power to resolve these questions, but hitherto, their computational expense has been prohibitive due to the extremely large dynamical range in length scales inherent to the problem. Consequently, early global simulations were run with parameter choices that, although unlikely to describe real events, made the runs feasible (S. Rosswog et al. 2008; H. Shiokawa et al. 2015). In these simulations, nearly all of the bound matter passes again through the apocenter region after its first return to the vicinity of the black hole. However, as the simulation parameters were not realistic, these results have not been widely accepted as relevant to observed TDEs.

Recently, the numerical barriers have been overcome by three different groups (T. Ryu et al. 2023b; D. J. Price et al. 2024; E. Steinberg & N. C. Stone 2024) using very different numerical methods, but all of them employing well-understood physics. In this paper, we will show that these simulations largely agree on where the bound debris goes after its first return to the vicinity of the black hole: >99% is placed on orbits extending to thousands of gravitational radii, while <1% is confined within distances comparable to the disrupted star’s pericenter.

In addition, we will outline the striking observational implications stemming from this consensus. Without the use of any adjustable parameters, they are in good agreement with typical observed values of the luminosity and spectral shape at the peak of the flare, the total radiated energy during the flare peak, the character of the long-term lightcurve, and the stellar and black hole masses most commonly inferred from detected events.

However, it is important to note that this model, although applicable to the majority of the TDE population, does not apply when the black hole mass $M_{\text{BH}} \gtrsim 10^7 M_{\odot}$. For these more massive black holes, the maximum stellar pericenter at which a total disruption takes place is $\lesssim 10 r_g$ ($r_g \equiv GM_{\text{BH}}/c^2$; T. Ryu et al. 2020b). In such cases, relativistic apsidal precession is so strong that it qualitatively changes the characteristic behavior of the debris.

We will first briefly summarize the relevant observational results, focusing on TDEs of the most commonly seen variety, those dominated by an optical/UV flare (Section 2). Next (in Section 3), we will remind readers of the tidal debris’ characteristic length scales, orbital energies, etc. Following these presentations of background, we will summarize the three new global simulations (Section 4). The heart of our work will appear in Section 5, where we demonstrate how the shared results of the simulations lead to important statements about both the underlying dynamics of TDEs and many of their observed properties. Our conclusions will then be summarized in Section 6.

2. A Brief Summary of Observations

2.1. The Optical Flare

In most optical/UV TDEs, the optical/UV flux rises quickly (over a few weeks) to a peak of $\sim 3 \times 10^{43} - 3 \times 10^{44} \text{ erg s}^{-1}$, followed by a lengthy (a few months) decline. The spectra are well fit by single-temperature Planck functions, whose typical temperatures are $\sim 3 \times 10^4 \text{ K}$ and corresponding blackbody emitting radii are 10^{14-15} cm (S. van Velzen et al. 2020; E. Hammerstein et al. 2023a). When lines are observed, their

typical width corresponds to $\sim 5000 \text{ km s}^{-1}$ (see, e.g., for a review S. Gezari 2021). For a black hole mass $\sim 10^6 M_{\odot}$, the scale of the emitting area is consistent with the scale of orbits with the speed inferred from the lines.

In some cases, the luminosity declines from its peak $\propto t^{-\alpha}$ with $\alpha \simeq 5/3$, the expected slope of the mass infall rate’s decline (M. J. Rees 1988; E. S. Phinney 1989). However, the entire sample exhibits a wider range of lightcurve power-law indices, $1 \lesssim \alpha \lesssim 3$ (E. Hammerstein et al. 2023a). Approximate integration of lightcurves yields a total radiated energy $\sim 10^{50.5 \pm 0.5} \text{ erg}$ (the ± 0.5 in the exponent refers to the standard deviation in the logarithm). At late times, years or more after the peak, the decay is much shallower. For those events observed $\gtrsim 0.5 \text{ yr}$ past the peak, although there is a good deal of scatter, the bolometric luminosity typically falls below the peak by a factor ~ 10 and the lightcurve levels out (S. van Velzen et al. 2019a, 2021; Y. Yao et al. 2023). The late-time radiated energy is therefore comparable to the prompt radiated energy.

2.2. X-Rays

Although there are a few dozen examples of TDEs whose peak X-ray luminosities are comparable to the peak optical/UV luminosities often seen, relatively few TDEs discovered by optical/UV flaring have been associated with X-ray flares, and when there are detectable X-rays during the brightest part of the flare, they are generally much less luminous than the optical/UV (R. Saxton et al. 2021; E. Hammerstein et al. 2023a). Nonetheless, the great majority of TDEs seen to produce X-rays, whether optically discovered or not, have rather soft spectra during the flare: when fitted by a Planck function, the characteristic temperature $kT \sim 50 - 100 \text{ eV}$ (R. Saxton et al. 2021). There is, however, a good deal of diversity in their lightcurves: in terms of how rapidly the X-rays decline (K. Auchettl et al. 2017), nonmonotonic behavior, and separation in time from any associated optical/UV flare (P. G. Jonker et al. 2020; T. Wevers et al. 2021, 2024; A. Malyali et al. 2024) or spectral changes (P. G. Jonker et al. 2020; S. Sazonov et al. 2021; G. A. Khorunzhev et al. 2022).

2.3. Radio

Radio emission has been observed both during the prompt phase and also at times months or even years after a TDE, sometimes even when there was no prompt emission (K. D. Alexander et al. 2020; A. Horesch et al. 2021; Y. Cendes et al. 2024). The luminosity of the observed radio signal is always much less than in the optical/UV or X-rays. In most cases, equipartition analysis indicates that their sources involve only a small fraction of the total energy⁴ in the system (K. D. Alexander et al. 2016; J. Krolik et al. 2016). It is generally thought that the radio emission takes place at large distances from the black hole, but there is considerable controversy over the nature of the outflow producing it (K. D. Alexander et al. 2016; J. Krolik et al. 2016; S. van Velzen et al. 2016; T. Matsumoto & T. Piran 2021). Because the radio source is dynamically decoupled from the bound material, we will not discuss it here.

⁴ When the TDE is jetted, as, for example, Swift J1644+57, equipartition analysis (B. A. Zauderer et al. 2011, 2013; E. Berger et al. 2012; R. Barniol Duran & T. Piran 2013; T. Eftekhari et al. 2018; A. Yalinewich et al. 2019) suggests that the energy of the emitting electrons is comparable to the energy content of the source producing other signals (e.g., the prompt X-rays).

3. Basic Quantities

Through dimensional analysis and simple physical arguments, the fundamental parameters of TDEs determine a set of characteristic distances, timescales, and orbital properties for the debris as it separates from the star. Although these undergird the topic, it is important to recognize that details omitted from their definitions significantly alter some of the scalings they imply.

3.1. Length Scales

At the most basic level, TDEs depend on the mass M_* of the star (generally stated in units of M_\odot), the mass of the black hole, M_{BH} (for which we adopt a fiducial value of $10^6 M_\odot$), and the pericenter of the star's orbit. Because there are very few stars whose orbital semimajor axes are comparable to the scale on which TDEs happen, the rate of TDEs is almost certainly dominated by stars whose orbits are extremely eccentric. In fact, most stars that become victims of TDEs are on effectively parabolic orbits; we will quantify this statement momentarily.

At the order-of-magnitude level, the criterion for the tidal gravity of the black hole to overwhelm the self-gravity of a star is

$$\frac{GM_{\text{BH}}R_*}{r_t^3} \gtrsim \frac{GM_*}{R_*^2}. \quad (1)$$

Thus, the order-of-magnitude tidal radius r_t is given by

$$\begin{aligned} r_t &= \frac{R_* M_{\text{BH}}^{1/3}}{M_*^{1/3}} = 7 \times 10^{12} m_{\text{BH},6}^{1/3} m_*^{0.55} \text{ cm} \\ &= 50 m_{\text{BH},6}^{-2/3} m_*^{0.55} r_g, \end{aligned} \quad (2)$$

where m_* is the stellar mass in solar masses, $m_{\text{BH},6}$ is the black hole mass in units of $10^6 M_\odot$, and $r_g \equiv GM_{\text{BH}}/c^2$ is the black hole's gravitational radius. Here and in the rest of the text, we describe the main-sequence mass-radius relation by the power law $R_* = 0.93 R_\odot m_*^{0.88}$ (T. Ryu et al. 2020c). Whenever m_* appears in a scaling relation, if its exponent is written as a decimal quantity, part of the m_* -dependence is through $R_*(m_*)$.

The tidal radius estimator r_t is based on an order-of-magnitude argument. Other radii relevant to tidal disruptions differ from it by factors of order unity. In particular, the critical radius within which a star can be completely disrupted is $\mathcal{R}_T = \Psi(M_*, M_{\text{BH}}) r_t$ (T. Ryu et al. 2020c, 2020d). The correction factor $\Psi(M_*, M_{\text{BH}})$ is defined in Appendix A. Although $\Psi(M_*, M_{\text{BH}})$ is of order unity, its dependence on the stellar mass and the black hole mass is important when estimating TDE rates.

3.2. Energy Scales and Orbital Properties

The specific orbital energy of the debris liberated from the star is conventionally estimated (M. J. Rees 1988) by

$$\begin{aligned} \Delta E_0 &= \frac{GM_{\text{BH}}R_*}{r_t^2} = \frac{G(M_{\text{BH}}M_*^2)^{1/3}}{R_*} \\ &= \frac{GM_{\text{BH}}}{r_t} \left(\frac{M_*}{M_{\text{BH}}} \right)^{1/3} = 2.3 \times 10^{-4} c^2 m_{\text{BH},6}^{1/3} m_*^{-0.213}. \end{aligned} \quad (3)$$

In other words, the orbital energy of the debris is, for typical parameters, $\sim 10^{-2}$ the potential energy near the nominal tidal radius. However, once again, detailed calculations

(J. A. P. Law-Smith et al. 2020; T. Ryu et al. 2020c, 2020d) have found that consideration of the internal density profile of main-sequence stars introduces order-unity correction factors: T. Ryu et al. (2020c) defined them by $\Xi = \Delta E / \Delta E_0$, where the energy range $-\Delta E < E < +\Delta E$ contains 90% of the debris mass. Details about the correction factor Ξ , including fitting formulæ for its dependence on M_* and M_{BH} , are provided in Appendix A.

For the star's orbit to be “effectively parabolic,” its specific binding energy should be much smaller than the debris specific energy, ΔE . This condition corresponds to an initial stellar semimajor axis much larger than the debris minimal semimajor axis a_0 (defined in Equation (4)), and to eccentricity much closer to unity than the debris' eccentricity (defined in Equation (5)).

The specific orbital energy also determines another characteristic length scale: the semimajor axis of the initial orbit traveled by the “most bound” matter:

$$\begin{aligned} a_0 &= \frac{GM_{\text{BH}}}{2\Delta E} = \frac{M_{\text{BH}}^{1/3} r_t}{2\Xi M_*^{1/3}} = \frac{M_{\text{BH}}^{2/3} R_*}{2\Xi M_*^{2/3}} \\ &= 3.26 \times 10^{14} \Xi^{-1} m_{\text{BH},6}^{2/3} m_*^{0.213} \text{ cm} \\ &= 2200 \Xi^{-1} m_{\text{BH},6}^{-1/3} m_*^{0.22} r_g. \end{aligned} \quad (4)$$

Consistent with the ratio $\sim 10^{-2}$ between ΔE and the gravitational potential near r_t , the orbital semimajor axis is $\sim 10^2 r_t$. Because the pericenter of all of the debris orbits is very nearly the stellar center-of-mass pericenter, and r_p is often $\lesssim r_t$, the large ratio between a_0 and r_t immediately implies that the debris orbits are extremely eccentric:

$$\begin{aligned} 1 - e &\leq 2(r_p/r_t) \Xi (M_*/M_{\text{BH}})^{1/3} \\ &\leq 0.02 (r_p/r_t) \Xi (m_*/m_{\text{BH},6})^{1/3}. \end{aligned} \quad (5)$$

Lastly, the energy also determines a characteristic timescale t_0 , the orbital period of the most bound matter:

$$\begin{aligned} t_0 &= \frac{\pi}{\sqrt{2}} \left(\frac{M_{\text{BH}} R_*^3}{GM_*^2 \Xi^3} \right)^{1/2} \\ &= 37 \Xi^{-3/2} m_{\text{BH},6}^{1/2} m_*^{0.32} \text{ d}. \end{aligned} \quad (6)$$

As m_* increases, the internal density profile of main-sequence stars becomes increasingly centrally concentrated. This causes Ξ to rise as a function of M_* , and the net result is for there to be almost no net trend in t_0 as M_* increases from $\simeq 0.1 M_\odot$ to $\simeq 10 M_\odot$ (T. Ryu et al. 2020c). On the other hand, the explicit scaling with M_{BH} is augmented by the implicit dependence on M_{BH} through Ξ , making $t_0 \propto m_{\text{BH},6}^{0.6}$.

This characteristic timescale is significant for (at least) two reasons. The first is that it is the characteristic timescale on which the debris revisits the vicinity of the black hole: the rate at which mass returns to near the stellar pericenter rises to a peak that occurs $\simeq t_0$ after the star's pericenter passage and then declines thereafter as $(M_*/3t_0)(t/t_0)^{-5/3}$. The second is that, as the orbital period of the debris, it also defines the growth time of the internal stresses capable of driving accretion through outward angular momentum transport. Nonlinear saturation of the MHD turbulence driven by the magnetorotational instability is generally thought to take ~ 10

orbital periods, which, in this instance, is $\sim 10t_0$, or ~ 1 yr for typical parameters.

3.3. Circularization and the Inverse Energy Crisis

The length scale where most of the mass is located dictates the implied efficiency of energy extraction. The conversion efficiency of kinetic to thermal energy at distance r from a black hole is:

$$\eta(r) \simeq \frac{GM_{\text{BH}}}{rc^2} = \frac{r_g}{r}. \quad (7)$$

For example, if, upon its first return to the black hole, the debris joins a compact disk with circular orbits of radius $\sim r_p$, the peak rate at which orbital energy is dissipated is

$$L_0 \sim \eta(r_p) \frac{M_*}{3t_0} \sim 10^{46} \left(\frac{25r_g}{r_p} \right) m_*^{0.68} \\ \times m_{\text{BH},6}^{-1/2} \Sigma^{3/2} \text{ erg s}^{-1}. \quad (8)$$

This is $\sim 10^2 \times$ larger than the luminosity typically observed in the prompt phase, a problem that has been called the ‘‘inverse energy crisis’’ (first discussed in T. Piran et al. 2015).

If this much light were generated over a surface comparable to that subtended by the inner regions of an accretion disk around a black hole, it would have a characteristic temperature

$$T_0 \sim \left(\frac{L_0}{\sigma_{\text{SB}} 2\pi r_p^2} \right)^{1/4} \sim 1 \times 10^6 \left(\frac{r_p}{25r_g} \right)^{-3/4} \\ \times m_*^{1/6} m_{\text{BH},6}^{-5/8} \Sigma^{3/8} \text{ K}, \quad (9)$$

where σ_{SB} is the Stefan–Boltzmann constant. This is $\sim 50 \times$ the observed optical/UV temperature (S. van Velzen et al. 2020; E. Hammerstein et al. 2023a). Typical observed velocities from motion at a few tens of r_g would be $\sim 30,000 \text{ km s}^{-1}$, about 10 times larger than implied by the measured emission-line widths.

Interestingly, all three problems, about the luminosity, temperature, and velocity, are solved if the apocenter, a_0 , were to replace the pericenter, r_p , as the place where kinetic energy of the flow is converted to heat.

4. Summary of Current Numerical Simulations

4.1. Realistic, Global Simulations

Explicit hydrodynamic simulations of what happens to the bound portion of the tidal debris are the best path toward understanding the fate of the returning matter stream and uncovering the observational implications of debris dynamics. Beginning with R. A. Nolthenius & J. I. Katz (1982), many numerical hydrodynamics simulations about various aspects of TDE evolution have been published. Unfortunately, relatively few had realistic initial conditions and were carried out long enough to be suitable for investigating the system as a whole. The prerequisites for a simulation to be genuinely realistic and global are to:

1. have a problem volume large enough to contain all of the bound debris (or at least that portion of it returning within a few t_0 of the disruption);
2. run for a time $\gtrsim t_0$;

3. consider a star on an effectively parabolic orbit (when this criterion is not satisfied, the orbit of the returning stream is dominated by the energy of the initial stellar orbit rather than by the disruption event);
4. self-consistently link the disruption itself with the post-disruption debris hydrodynamics;
5. assume parameters that might apply to observed events.

Three simulations stand out as satisfying all of these criteria. We list them in order of their publication dates. T. Ryu et al. (2023b) employed two fixed grids, one a small box following the star’s orbit, the other a large volume surrounding the black hole. Simultaneous evolution on the two grids was coordinated through a ‘‘multipatch’’ system (H. Shiokawa et al. 2018; M. J. Avara et al. 2024). The programs running on both grids solve the general relativistic hydrodynamics equations; the one responsible for the star adds relativistically consistent stellar self-gravity. T. Ryu et al. (2023b) considered a $3M_\odot$ star, whose internal structure was taken from an MESA model of a middle-aged main-sequence star, and a $10^5 M_\odot$ black hole. The equation of state included LTE radiation pressure, but there was no computation of radiation transfer because, for these parameters, the cooling time was always very long compared to the evolution time. The duration of this simulation was $3t_0$. E. Steinberg & N. C. Stone (2024) solved the equations of Newtonian hydrodynamics and radiation transport in the flux-limited diffusion approximation on a moving mesh. Stellar self-gravity was computed via a quadrupole moment tree, and the black hole’s gravity was approximated as a Paczynski–Wiita potential with a softening term. They chose a $1M_\odot$ star and a $10^6 M_\odot$ black hole, but described the internal structure of the star as an $n = 3/2$ polytrope, i.e., an isentropic structure for a gas with an adiabatic index of $5/3$. This simulation ran for $\approx 1.4t_0$. The third (D. J. Price et al. 2024) was produced by a smoothed particle hydrodynamics (SPH) code with relativistic hydrodynamics in a Schwarzschild spacetime and the same equation of state as in T. Ryu et al. (2023b). Their star’s initial structure was the same as in E. Steinberg & N. C. Stone (2024), but its self-gravity was calculated as an integral over the Newtonian Green’s function for the Poisson Equation with a softening term to smooth short length-scale fluctuations. The simulation covered a time up to $\simeq 9t_0$. All three of these simulations provided resolution capable of describing the smallest relevant structures, whether in the disrupting star or in shocks within the debris flow. E. Steinberg & N. C. Stone (2024) presented an especially detailed discussion of these issues, but the strong agreement in results between the three suggests that the other two were comparably well resolved.

Three other simulations are also of interest, but each fails one or two of the criteria. The first (H. Shiokawa et al. 2015) passed all of the criteria but the final one: they investigated the disruption of a $0.64M_\odot$ white dwarf by a $500M_\odot$ black hole, choosing these parameters because they reduced the contrast in length scales, thereby diminishing the computational cost. Like the work of T. Ryu et al. (2023b), this simulation treated the problem in terms of fully general relativistic dynamics and included radiation pressure through its LTE contribution to internal energy. It also had the longest duration of all simulations published to date: $13t_0$. The second (A. Sadowski et al. 2016) combined general relativistic hydrodynamics with Newtonian stellar self-gravity. Its parameters, however, were somewhat special: the star began on a bound orbit with $e = 0.97$, so that its specific orbital energy was actually greater

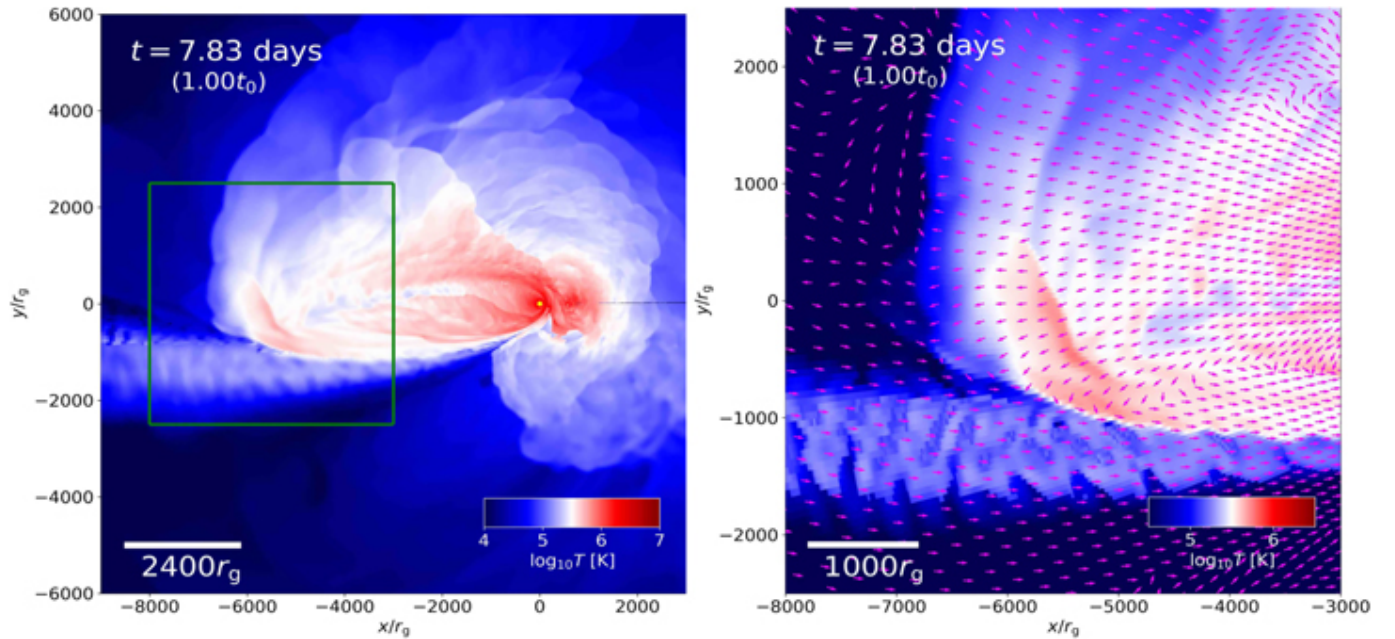


Figure 1. Temperature in the orbital plane in a logarithmic color scale (different scales in the two images), on large scales (left) and small (right); both taken from T. Ryu et al. (2023b). The green box in the left panel shows the boundaries of the zoomed-in right panel. Arrows in the right panel show the direction of gas flow.

in magnitude than ΔE of the debris. In addition, the star’s pericenter was at $7r_g$, so this simulation probed the relatively small phase space associated with strong apsidal precession. Lastly, the duration of the simulation was only $\simeq 0.3t_0$. Third, Z. L. Andalman et al. (2022), much like A. Sadowski et al. (2016), used Newtonian SPH to generate tidal debris and then general relativistic hydrodynamics to study its further motions for an event in which the stellar pericenter was $7r_g$, but the star was on an effectively parabolic orbit. The duration was only $\simeq 0.03t_0$. Thus, it, too, cannot be directly applied to the most common events, both because it treated a TDE with an exceptionally small pericenter and because it ran for only a brief time.

4.2. Consensus Dynamical Results

All four of the simulations studying disruptions with pericenters $>10r_g$ found the same principal dynamical features. The most prominent of these are several quasi-standing shocks. As predicted by C. R. Evans & C. S. Kochanek (1989) and C. S. Kochanek (1994), the convergence of debris streams whose orbital planes are slightly different creates a shock near the pericenter, dubbed the “nozzle shock.” Compared to the orbital speed, this is a weak shock, with speed at early times only $\sim (M_*/M_{\text{BH}})^{1/3}v_{\text{orb}}$ and therefore able to dissipate only $\sim 10^{-4}m_*^{2/3}m_{\text{BH},6}^{-2/3}$ of the orbital kinetic energy near pericenter. Although the nozzle shock initially comprises a pair of roughly horizontal shocks, the shock fronts tilt over time. This results in a somewhat greater dissipation efficiency, perhaps reaching, at its greatest, $\sim (M_*/M_{\text{BH}})^{1/3}$ of the pericenter-region kinetic energy (H. Shiokawa et al. 2015). A small fraction of the matter encountering the nozzle shock is deflected inward as the shock redistributes angular momentum (H. Shiokawa et al. 2015; T. Ryu et al. 2023b; E. Steinberg & N. C. Stone 2024; and D. J. Price et al. 2024; G. Lodato, 2025 private communication), carrying matter to smaller radii at a rate that is at most $\lesssim 0.01M_*/t_0$. The inward-moving matter does not instantaneously settle into a “normal” circular-orbit

accretion disk. Instead, the substantial eccentricity of the deflected matter’s orbits leads to further shocks at radii inside pericenter (T. Ryu et al. 2023b; D. J. Price et al. 2024; E. Steinberg & N. C. Stone 2024). The pericenters of the matter gaining angular momentum move outward. When this matter returns to the pericenter region, it shocks at a larger radius. Consequently, the radial extent of the nozzle shock gradually stretches, reaching $\sim 400r_g \sim 4r_p$ by $t \sim 3t_0$ (T. Ryu et al. 2023b).

Debris that has passed through the nozzle shock swings back out toward an apocenter that is slightly smaller because of the orbital energy dissipated in the shock; its natal specific angular momentum is so small that the angular momentum exchange in the shock hardly affects the apocenter. Because the disruption of the star takes place across a range of distances from the black hole (roughly from $r \simeq r_p$ to $r \simeq 20r_p$; T. Ryu et al. 2020d) and because of relativistic effects in both the tidal stress and the orbits, the lines of apsides of the debris orbits stretch across a range of angles $\sim 10^\circ$ (H. Shiokawa et al. 2015). When the range of angles is this small and the orbits are highly eccentric, the streams intersect near apocenter (see also the related geometric argument of L. Dai et al. 2015). Two views of these shocks are presented in Figure 1, which highlights shock locations by portraying temperature (see also Figure 1 of E. Steinberg & N. C. Stone 2024).

Unlike the nozzle shock, the angle between the flows shocking against one another near apocenter is large. Consequently, the energy dissipated is comparable to the local orbital kinetic energy. In rough terms, the kinetic energy near apocenter is a fraction $1 - e$ of the kinetic energy near pericenter, and we have already estimated that $1 - e \simeq 0.02(r_p/r_i) \Xi(m_*/m_{\text{BH},6})^{1/3}$. The energy per unit mass dissipated in an apocenter shock is then $\sim \Delta E$, comparable to or greater than that of the nozzle shock (H. Shiokawa et al. 2015; E. Steinberg & N. C. Stone 2024).

The precise location(s) of the apocenter shock(s) change over time. Because the earliest matter to return is the most

bound, and therefore has the smallest apocenter, at early times this shock moves outward. At later times, after some material has gone around more than once and lost some orbital energy in the nozzle and apocenter shocks, the apocenter shock moves inward. In addition, as the debris orbits change shape, other shocks form at radii comparable to a_0 , but farther from the path of newly returning debris (H. Shiokawa et al. 2015; T. Ryu et al. 2023b; E. Steinberg & N. C. Stone 2024). Throughout these events, matter that is returning for the first time commingles with matter that has already completed one or more orbits; in other words, from very early on, the dynamics are poorly approximated by considering only a stream wrapping around the black hole once and then encountering a newly arriving stream. This is one of the reasons that encompassing at least the majority of the bound debris is a prerequisite for simulation credibility.

Although there have been suggestions in the literature that the radiation pressure of light emitted from an inner accretion disk (B. D. Metzger & N. C. Stone 2016) or arising from “stream-stream” shocks like the apocenter shocks (W. Lu & C. Bonnerot 2020; C. Bonnerot et al. 2021) could lead to unbinding a significant amount of mass, there is little evidence for this in global simulations; over the first $\sim(1 - 2)t_0$, the amount of mass converted from bound to unbound is $\lesssim 0.01M_*$ (T. Ryu et al. 2023b; E. Steinberg & N. C. Stone 2024).⁵

Lastly, despite the expectation in the traditional model that matter is accreted onto the black hole as fast as it returns from its first visit to apocenter, and therefore the possible rate of energy release is highly super-Eddington, the two global simulations with astrophysically relevant parameters find that radiation forces are generally significant, but rarely exceed the gravitational force (i.e., the flux at most approaches the Eddington level). That this is so is particularly striking in the case treated by T. Ryu et al. (2023b) because the peak mass-return rate is so high that it would yield a heating rate $\sim 5000L_E$ if the efficiency were ~ 0.1 .

4.3. Consensus Structural Results

As already stressed in Section 1, the simple question “Where is the tidal debris?” is fundamental to any consideration of its observable phenomenology. When speaking about the bulk of the bound matter that has already returned from its first visit to apocenter, the simulations give a consistent answer: at a radius $\sim a_0$. Given the dynamical picture already summarized, it could hardly be anything else: its orbital energy has been diminished by at most a factor of order unity. Because a_0 depends very weakly on both the black hole mass and the star mass (see Equation (4)), most of the bound mass—even when it settles into an accretion flow—remains at distances $\gtrsim 2500r_g$ from the black hole. For example, at $t \simeq 1.4t_0$ (the endpoint of the E. Steinberg & N. C. Stone 2024 simulation), $\approx 3/4$ of the accretion flow mass is $> 5000r_g$ from the black hole in both that simulation (E. Steinberg, private communication) and the simulation of T. Ryu et al. (2023b). At $t = 3t_0$, the endpoint of the latter simulation, that fraction has hardly changed.

The vertical mass distribution for all of the bound mass that has passed through at least one shock is also simply described:

⁵ D. J. Price et al. (2024) found that an expanding “Eddington envelope” carries $\sim 2/3$ of the initially bound debris outward, but did not state what fraction of this envelope is unbound.

it is geometrically thick. As already estimated, the apocenter shocks generically dissipate an energy similar to the net energy of the debris orbits, ΔE . It immediately follows that in energetic terms, the gas is supported as much by pressure (largely radiation) as by rotation.

The characteristic radial scale remains close to a_0 , but the characteristic eccentricity changes substantially, dropping to ~ 0.5 . This is due primarily to the orbital energy lost by the gas in all of the shocks, but is aided by the angular momentum gained when the nozzle shock removes angular momentum from the fluid deflected inward and transfers it to the fluid that remains on orbits going out to the $r \sim a_0$ region.

Although the great majority of the bound debris stays relatively far from the black hole, small amounts can find their way much closer. Again, the three extant simulations give similar results: at $t \simeq 1.4t_0$, both T. Ryu et al. (2023b) and E. Steinberg & N. C. Stone (2024) found $\sim 2\text{--}5 \times 10^{-3}M_*$ at radii $\lesssim r_p/2$. Both numbers, as well as the fate of this matter, are uncertain due to the inner cutoffs employed by these simulations (see the next subsection for details). Although D. J. Price et al. (2024) did not quote a figure for the mass close to the black hole at $t \sim t_0$, their Figure 2 shows only a very small fraction of the total mass this close even at $t \simeq 9t_0$.

4.4. Limitations

To close this section, we acknowledge three limitations to the guidance we can derive from the existing global simulations. First, two of them impose unrealistic dynamics near the black hole. T. Ryu et al. (2023b) placed an outflow boundary condition at a spherical radius $40r_g$ from the black hole’s center. This means they cannot say what happens to matter passing through that surface, and they likely overestimated the net rate at which matter crosses the boundary. Rather than place a sharp boundary around the black hole, E. Steinberg & N. C. Stone (2024) instead forced the gravitational potential to increase linearly with radius from the black hole out to $30r_g$, where it switches to a Paczynski–Wiita form. The impact of this policy is to make the dynamics of gas close to the black hole unphysical: fluid elements have the wrong velocity and follow incorrect orbits. The motivation for both policies is to avoid excessively short time steps. Like T. Ryu et al. (2023b), D. J. Price et al. (2024) employed general relativistic hydrodynamics (except for the star’s self-gravity), but differed by not requiring any central cutout. Thus, this simulation may be more reliable than the other two for matter passing close to the black hole.

The second limitation is crude approximations to time-dependent radiation transfer. In the simulations by T. Ryu et al. (2023b) and D. J. Price et al. (2024), there is no transfer at all: the radiation is assumed to be in LTE everywhere and at all times. Because the parameters of the T. Ryu et al. (2023b) simulation led to a particularly large ratio of cooling time to evolution time, this was not a bad approximation, but it would break down for larger M_{BH} and/or smaller M_* . Although D. J. Price et al. (2024) allowed no radiation transport during their hydrodynamical simulation, they estimated the radiated luminosity in post-processing. To do so, they solved 1D time-steady transfer equations (even though the photon diffusion time was often longer than the evolution timescale) in which they assumed the total opacity had the Thomson scattering value, but was purely absorptive. This procedure likely overestimates the luminosity. E. Steinberg & N. C. Stone (2024)

solved a time-dependent radiation transfer equation along with the hydrodynamic equations, but in a very simplified form: in the gray flux-limited diffusion approximation, with Thomson scattering opacity. In much of the volume occupied by debris, the density is low enough to support the approximation of Thomson opacity, but in the denser regions, it is likely to underestimate significantly the Rosseland mean (S. Hirose et al. 2014). Moreover, the flux-limited diffusion formalism always directs the flux along the radiation intensity gradient, but this is frequently wrong near and outside the photosphere. Errors of this sort are particularly problematic for radiation-driven outflows and geometrically complicated photospheres. Given these uncertainties, we note that our estimates below of the energy dissipation rate are more robust than those of the luminosity and temperature. Nonetheless, for the angle-integrated bolometric luminosity, the time-dependent solution of E. Steinberg & N. C. Stone (2024) should provide the best estimate of the three; unfortunately, it ran for only $\simeq 1.4t_0$.

The third limitation is that all three simulations considered events with $r_p > 10r_g$. When the pericenter is smaller, relativistic apsidal precession in a single pericenter passage is a radian or more, so that strong shocks take place close to the pericenter scale, and a great deal more heat is dissipated than when the apsidal precession is weaker and the shocks take place much farther away. This contrast can qualitatively change the character of the event, especially when $r \lesssim 6r_g$ (T. Ryu et al. 2023a). Pericenter passages closer than $\sim 10r_g$ occur in only a small fraction of disruptions by black holes with mass $\lesssim 10^7 M_\odot$, but in nearly all flare-producing events with $M_{\text{BH}} \gtrsim 10^7 M_\odot$ (J. Krolik et al. 2020; T. Ryu et al. 2020b). For this reason, the consensus results we focus on here may need significant revision when $M_{\text{BH}} \gtrsim 10^7 M_\odot$, and our statements about scaling relations may fail for $M_{\text{BH}} \gtrsim 10^7 M_\odot$.

4.5. Summary of Simulation Results

For many purposes, these results can be summarized very concisely by two key statements. It is worth remarking that their import is in excellent agreement with the results of the simulation reported by H. Shiokawa et al. (2015).

First, by a few t_0 , when the majority of the bound mass has returned from its first passage through apocenter, a new structure has been created that is hot, irregular, crudely elliptical, and geometrically thick. It might be called an ‘‘accretion flow,’’ but it is very different from a classical ‘‘accretion disk.’’ During its formation, the orbits of fluid elements change by angular momentum exchange and energy dissipation in shocks, but once the accretion flow is formed, these shocks diminish in strength.

Second, that $\gtrsim 99\%$ of the debris mass remains $\sim 10^3\text{--}10^4 r_g$ from the black hole at times a few t_0 after disruption immediately implies that ‘‘circularization,’’ in which debris mass is placed on roughly circular orbits at radii $\sim 2r_p$ from the black hole, can be accomplished on a timescale $\sim t_0$ for only a very small fraction of the mass. The accretion rate onto the black hole must therefore be at least 2 orders of magnitude smaller than the mass fallback rate, in sharp contradiction to the traditional model. This fact follows from the lack of any mechanism to remove sufficient energy from the debris; both the dissipation of orbital energy into heat and the radiation of heat by photons are far too slow (see also Section 5.3) to permit all but a

small fraction of the debris mass to settle quickly (on the $\sim t_0$ timescale) into orbits near the black hole.⁶

5. Implications

The shared results of these simulations regarding the location of the debris have many implications for our understanding of TDEs, both in terms of conceptual framework and specific observational predictions. Remarkably, the simple fact of where the debris mass is deposited leads to strong predictions about many aspects of TDE phenomenology. Moreover, as we are about to show, these predictions are, without any fine-tuning, in agreement with many of the most striking features of these events.

5.1. The Energy Budget

As commented previously (Section 3.3), the distance between the black hole and the debris is directly connected to the energy available to radiate. With nearly all of the debris remaining (at times a few t_0 after the disruption) at a distance $\sim a_0$, the relevant dissipative efficiency is

$$\eta(a_0) \simeq \frac{GM_{\text{BH}}}{a_0 c^2} \simeq \frac{r_g}{a_0} \simeq 4.5 \times 10^{-4} \Xi m_{\text{BH},6}^{1/3} m_\star^{-0.21}. \quad (10)$$

The total heat released is then

$$E_{\text{diss}} \simeq \eta(a_0) (M_\star/2) c^2 \simeq 4 \times 10^{50} \Xi m_{\text{BH},6}^{1/3} m_\star^{0.79} \text{ erg}, \quad (11)$$

right in the middle of the observed radiated energy distribution. In fact, the total dissipated energy found by the simulations is closely consistent with this estimate.

It is possible that the $\lesssim 1\%$ of M_\star deflected inside r_p adds to the dissipated energy, but as we will demonstrate in Section 5.7, in terms of bolometric luminosity, it can at most augment the light from the bulk of the debris by a factor of order unity. In other words, the three simulations support the suggestion at the end of Section 3.3 about placing the debris at a distance $\sim a_0$ rather than $\sim r_p$.

5.2. Emission-line Widths

Another consequence of our more robust knowledge of the debris’ location is that it implies an orbital speed for the debris, and therefore the width of any atomic line features in its spectrum. Although the orbital speed varies around an elliptical orbit, the scale of the speed is nonetheless determined by its semimajor axis:

$$v_{\text{orb}} \simeq c(r_{\text{img}}/a_0)^{1/2} = 6400 \Xi^{1/2} m_{\text{BH},6}^{1/6} m_\star^{-0.11} \text{ km s}^{-1}. \quad (12)$$

This characteristic speed depends extremely weakly on both M_{BH} and M_\star . It is in the center of the measured $\text{H}\alpha$ FWHM line width distribution for TDEs without Bowen N III lines, and is about half the median FWHM when Bowen N III lines are present (P. Charalampopoulos et al. 2022), suggesting that perhaps Bowen lines are associated with events having larger m_\star and smaller $m_{\text{BH},6}$.

⁶ E. Steinberg & N. C. Stone (2024) extrapolated from the data of their simulation to argue that the total heating by shocks grows exponentially after $t \simeq t_0$. However, their simulation did not extend long enough to test this extrapolation, and it is not seen in either of the two longer simulations, those of T. Ryu et al. (2023b) and D. J. Price et al. (2024).

5.3. Optical Depth and the Cooling Time

The optical depth τ of the debris is, of course, immediately determined by the density distribution. Because the mass-return rate is $\propto t^{-5/3}$ after its peak, only a minority of the bound mass has returned to the vicinity of the black hole by a few t_0 after the disruption. In addition, the mass that has returned spends most of its time near its orbital apocenter, $\gtrsim 2a_0$ from the black hole. Consequently, the optical depth varies as a function of position. For example, as shown in T. Ryu et al. (2024), only a fraction $f(a_0) \simeq 15\%$ of the bound mass can be found within a distance a_0 of the black hole at $t = t_0$. Over the span of radii where most of the mass is located, $0.3a_0 \lesssim r \approx 3a_0$, $f(r) \propto r^{1+\epsilon}$, where ϵ is small and positive at $t = t_0$, but small and negative by $t = 3t_0$. If κ is the gas's Rosseland mean opacity and κ_T is the Thomson opacity, at $t = t_0$ the characteristic vertical optical depth to the midplane of a circular disk with radius $\sim a_0$ is

$$\tau_0 \approx 80 [f(a_0)/0.15] \Xi^2 (\kappa/\kappa_T) m_{\text{BH},6}^{-4/3} m_*^{0.55}. \quad (13)$$

Because $a_0 \approx 3.5 \times 10^{14} \Xi^{-1} m_{\text{BH},6}^{2/3} m_*^{0.22}$ cm, the basic dynamics of the bound debris automatically create a photosphere on a radial scale $\sim 10^{14.4 \pm 0.5}$ cm, just as inferred from the radiating area associated with the optical/UV blackbody. However, it is important to note that, as shown by the simulations, the photosphere can be far from spherical, as the density distribution is both flattened and nonaxisymmetric (T. Ryu et al. 2024; E. Steinberg & N. C. Stone 2024).

In disk geometry, the photon diffusion time is given by $(\tau + 1)h/c$, where h is the disk's vertical scale height and τ is the optical depth across a distance h (T. Piran et al. 2015; T. Ryu et al. 2020a). Because the radiation energy density is generally larger than the gas thermal energy, the characteristic cooling time for the debris within a distance r of the black hole is then

$$t_{\text{cool}} \approx 10 \left[\frac{f(r)}{0.15} \right] \left(\frac{h}{r} \right) \left(\frac{a_0}{r} \right) \times \left(\frac{\kappa}{\kappa_T} \right) m_{\text{BH},6}^{-2/3} m_*^{0.77} \Xi \text{ days}. \quad (14)$$

In units of t_0 , it is (T. Piran et al. 2015; T. Ryu et al. 2020a):

$$\begin{aligned} \frac{t_{\text{cool}}}{t_0} &\approx f \frac{h}{r} \frac{G^{1/2} \kappa M_*^{8/3} \Xi^{5/2}}{2^{3/2} \pi^2 M_{\text{BH}}^{7/6} R_*^{5/2}} \\ &\approx 0.26 \left(\frac{f}{0.15} \right) \left(\frac{h}{r} \right) \left(\frac{\kappa}{\kappa_T} \right) \\ &\quad \times \Xi^{5/2} m_{\text{BH},6}^{-7/6} m_*^{0.47}. \end{aligned} \quad (15)$$

The simulation results are consistent with this estimate. For example, E. Steinberg & N. C. Stone (2024) found that their proxy for the volume-integrated dissipation rate varies in a way not too different from the luminosity estimated by the flux-limited diffusion approximation (essentially equivalent to our t_{cool} estimate), but can occasionally depart from it by as much as a factor ~ 10 .

Fortuitously, $t_{\text{cool}}/t_0 \approx 1$ for our fiducial parameters. Because, as we have already mentioned, T. Ryu et al. (2024) found that $f(r) \propto r^{1+\epsilon}$, the characteristic cooling time inside the photosphere varies only slowly with radius, $\propto r^\epsilon$. When $m_{\text{BH},6} \gtrsim 1$, $t_{\text{cool}} < t_0$, so photon losses respond quickly to the

heating rate throughout the debris and the luminosity matches the total heating rate. Within a time $\sim t_0$, radiation can vent enough heat to let the flow settle closer to its equatorial plane. On the other hand, for encounters with a relatively low-mass black hole, the photon diffusion time is long relative to the heating time, making cooling inefficient. In addition, in this slow-cooling regime, the internal transport of radiation is not in a steady state. In other words, over a time $\sim t_0$, the gas retains much of its heat content—i.e., its heat content evolves adiabatically—until close to the time its orbit carries it through the photosphere or it encounters another shock.

Because radiation transport in the slow-cooling regime is time dependent, simple estimates of the luminosity, generally based on time-steady transfer, are subject to significant uncertainty. However, in this context, a simple estimate of the cooling time of individual fluid elements combined with the adiabaticity of the slow-cooling regime suggests that the luminosity of a given fluid element is held approximately constant as it moves around an orbit (G. Svirski et al. 2017). Estimated in this way, the luminosity released on a radial scale r is $L(r) \sim P_{\text{rad}} r^2 c/\tau$, where P_{rad} is the radiation pressure. With $P_{\text{rad}} \propto r^{-4}$ when the volume of a moving fluid element is $\propto r^3$, as it is here due to the rough constancy of h/r , for a specific fluid element $\tau \propto r^{-2}$. It follows that $L(r)$ is approximately independent of r . Additionally, as we will show in the next subsection, the heating rate in TDEs links this luminosity to the Eddington luminosity.

5.4. Flare Luminosity, Effective Temperature, and Flare Duration: Cooling Fast and Slow

5.4.1. Luminosity

The mass distribution also determines the luminosity. As argued in Section 3.3, the depth of the potential well specifies the energy available; the luminosity follows from combining the total energy with the heating time (effectively $\sim t_0$) and the cooling time (as just estimated). Rather than being the usual relativistic radiative efficiency times the mass fallback rate, $\sim \eta(10r_g) \dot{M}_{\text{peak}} c^2$, the rate at which energy is dissipated is $L_{\text{peak,diss}} \sim E_{\text{diss,peak}}/t_0 \sim (r_g/a_0) \dot{M}_{\text{peak}} c^2$.⁷ The heating efficiency for the bulk of the debris is much smaller than the canonical relativistic accretion value because the gravitational potential where the apocenter shocks take place is shallower by a factor $\sim 10r_g/a_0$. Consequently, instead of the peak dissipation rate being extremely super-Eddington, $\sim 2 \times 10^{46} \Xi^{3/2} m_{\text{BH},6}^{-1/2} m_*^{0.66} \text{ erg s}^{-1}$, it is

$$\begin{aligned} L_{\text{diss, peak}} &\simeq \eta(a_0) \frac{M_* c^2}{3t_0} \\ &\simeq 8.6 \times 10^{43} \Xi^{5/2} m_{\text{BH},6}^{-1/6} m_*^{0.47} \text{ erg s}^{-1} \\ &\simeq 0.6 \Xi^{5/2} m_{\text{BH},6}^{-7/6} m_*^{0.47} L_E(M_{\text{BH}}). \end{aligned} \quad (16)$$

This much lower heating rate is greater than Eddington only for black holes with masses $\lesssim 5 \times 10^5 m_*^{0.38} M_\odot$, and even then it exceeds Eddington by much less than the expectation based on relativistic efficiency.

To translate the rate at which energy is dissipated into a radiated luminosity requires consideration of both the cooling

⁷ Note that the $f(r)$ factor appearing in the optical depth is not relevant here because this quantity relates to the rate at which mass returns, not to how much resides within a given radius.

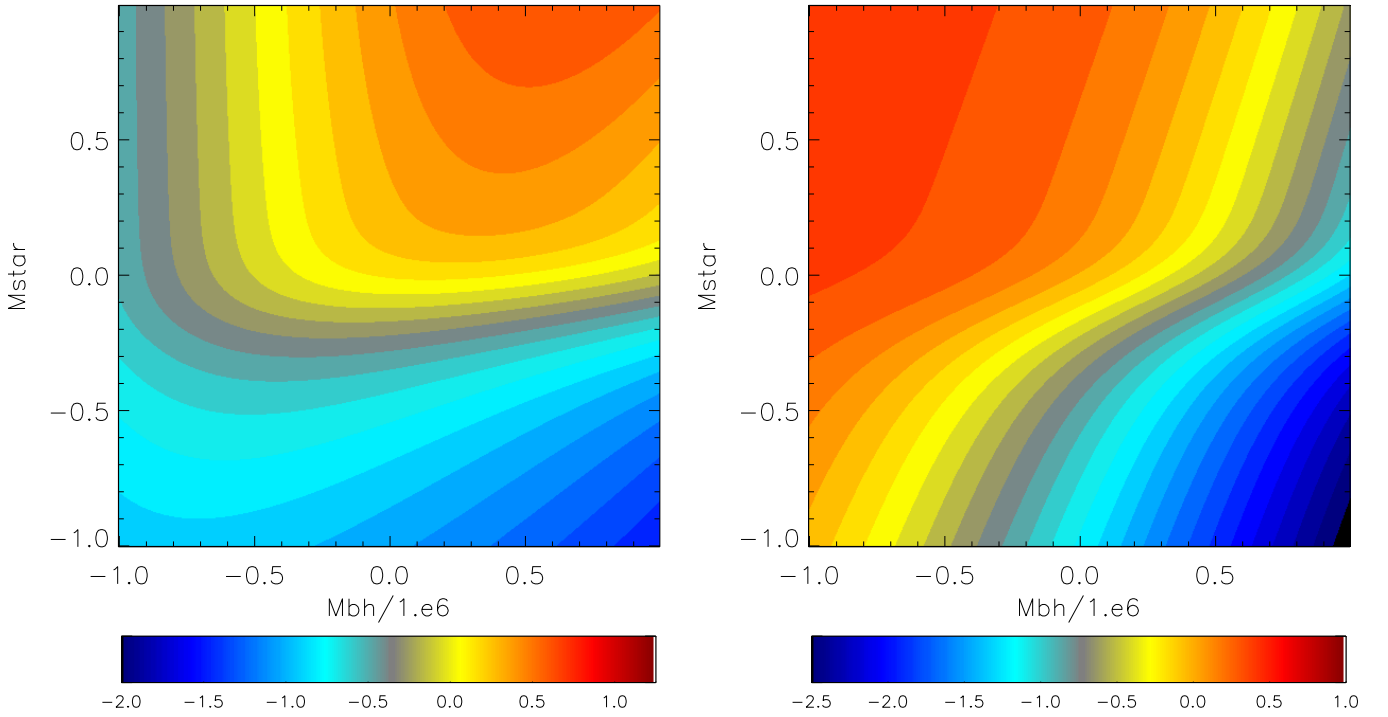


Figure 2. Peak radiated luminosity as a function of $M_{\text{BH},6}$ and m_* on a logarithmic scale ranging from 0.1–10 for both quantities. We assume $h/r = 0.3$, following the $t = t_0$ curve in Figure 10(d) of T. Ryu et al. (2024). Left panels: in units of 10^{44} erg s^{-1} . Right panels: in units of L_E .

time (see Equation (14)) and the duration of the heating, which is $\sim t_0$ for the bulk of the bound debris during the flare. The radiated luminosity $L_{\text{rad}} = L_{\text{diss}}$ when the cooling time is shorter than the time, i.e., t_0 , in which the heat is dissipated. On the other hand, when $t_{\text{cool}} > t_0$, the radiated luminosity is reduced by a factor $\sim t_0/t_{\text{cool}}$ relative to the heating rate L_{diss} . The peak luminosity (i.e., at $t = t_0$, when T. Ryu et al. 2024 found the cylindrical radius of the photosphere is at $r \approx a_0$) can then be written in a combined form that approximates both the slow- and fast-cooling regimes:

$$L_{\text{rad,peak}} = \frac{L_{\text{diss,peak}}}{1 + t_{\text{cool}}/t_0} \simeq 8.6 \times 10^{43} \frac{\Xi^{5/2} m_{\text{BH},6}^{-1/6} m_*^{0.47}}{1 + 0.26(f/0.15)(h/r)\Xi^{5/2} m_{\text{BH},6}^{-7/6} m_*^{0.47} (\kappa/\kappa_T)} \text{ erg s}^{-1}. \quad (17)$$

In the limit of $t_0 \ll t_{\text{cool}}$, the peak luminosity is limited to roughly the Eddington luminosity and is therefore independent of M_* (see Appendix B):

$$L_{\text{rad,peak}} \simeq \frac{2L_E}{(f/0.15)(h/r)(\kappa/\kappa_T)} \quad \text{for } t_0 \ll t_{\text{cool}}. \quad (18)$$

Note that $L_{\text{rad,peak}}$ may be reduced further if the density in the debris is high enough for the Rosseland mean opacity to exceed the Thomson value. This adjustment could be important because, at the expected temperature range ($\sim 1\text{--}3 \times 10^4$ K), atomic features can significantly augment electron scattering when the density is $\gtrsim 10^{-10}$ gm cm^{-3} (see the opacity calculations of S. Hirose et al. 2014).

The net result for the dependence of $L_{\text{rad,peak}}$ on M_{BH} and M_* is shown in Figure 2. In terms of the absolute flare luminosity (left panel), the greater mass of debris available from more massive stars often creates a higher radiative output. For this

reason, the highest luminosities generally correspond to the largest values of M_* . However, this no longer is the case when the larger amount of mass also means a greater optical depth and longer photon diffusion time—which occurs when the black hole mass is smaller. This is why the peak luminosity is smaller, even for the most massive stars, when M_{BH} is comparatively small, and hardly depends at all on m_* when $m_{\text{BH},6} \lesssim 0.5$ and $m_* \gtrsim 1$. On the other hand, larger black hole mass leads to a longer time over which radiation of nearly the same amount of energy takes place, driving down the peak luminosity for large M_{BH} . In the end, the highest luminosity is produced by moderate mass black holes ($M_{\text{BH}} \sim 1\text{--}5 \times 10^6 M_\odot$) and stars of the highest mass. The least luminosity occurs for particularly high-mass black holes and low-mass stars. Thus, for low M_{BH} the optical/UV peak luminosity is $\propto M_{\text{BH}}$ and almost independent of M_* , while for higher black hole mass, the luminosity increases rapidly with M_* and decreases slowly with M_{BH} . The division between “low” and “high” M_{BH} corresponds to the peak luminosity for any particular M_* , a value ranging from $\sim 1 \times 10^{43}$ erg s^{-1} for $M_* \sim 0.1 M_\odot$ to $\sim 1 \times 10^{45}$ erg s^{-1} for $M_* \sim 10 M_\odot$.

These predicted peak luminosities are closely consistent with the peak luminosity estimated directly from simulation data (on the basis of local cooling times by T. Ryu et al. 2024, time-dependent radiation transfer in the flux-limited diffusion approximation by E. Steinberg & N. C. Stone 2024, and instantaneous shock heating by D. J. Price et al. 2024). In all cases, the peak luminosity is predicted by our approximate expression to be $\simeq 1 \times 10^{44}$ erg s^{-1} , and this coincides with the simulation-based estimates. Note that the parameters of the disruption treated by E. Steinberg & N. C. Stone (2024) and D. J. Price et al. (2024) were the same ($M_* = 1 M_\odot$, $M_{\text{BH}} = 1 \times 10^6 M_\odot$), whereas T. Ryu et al. (2024) studied a case with $M_* = 3 M_\odot$ and $M_{\text{BH}} = 1 \times 10^5 M_\odot$.

More importantly, for $\sim 0.3 \lesssim m_* \lesssim 3$, they are closely consistent with the peak luminosities exhibited by the bulk of the observed cases (see Section 2 and the references cited there). Such good agreement with the observed peak luminosities gives very strong support to this picture because its prediction of the luminosity scale has no free parameters or guessed initial conditions for the debris; it is based entirely on physical calculations beginning with a main-sequence star passing a black hole. On the other hand, a small fraction of optical/UV TDEs shows still higher luminosities, reaching as high as $5 \times 10^{45} \text{ erg s}^{-1}$ (E. Hammerstein et al. 2023a). As explained in Section 5.8, very luminous events are over-represented in a magnitude-limited sample, so their real fraction is significantly smaller than the fraction observed. Because the black hole masses associated with these very luminous events tend to be $\gtrsim 10^7 M_\odot$ (E. Hammerstein et al. 2023b; Y. Yao et al. 2023; A. Mummery et al. 2024), we speculate that these are the rare TDEs in which the star plunges to $r_p \lesssim 10 r_g$, the large apsidal precession regime described at the end of Section 4.4. The different dynamics of that regime may lead to their higher luminosity.

The relationship between luminosity, stellar mass, and black hole mass is simplified considerably when the luminosity is measured in Eddington units (Figure 2, right panel). In the very long cooling time limit, the photon output is regulated to be several times L_E : this regime is found for almost all M_* when the black hole mass is small. For sufficiently high black hole mass, $L_{\text{rad,peak}}/L_E$ falls steadily but begins that fall at higher M_{BH} when M_* is greater.

5.4.2. Effective Temperature

To zeroth order, we may expect a thermal spectrum for the radiation from the photosphere of the debris, although a variety of stellar-atmosphere features are likely. Combining our estimate of $L_{\text{diss,peak}}$ with our estimate of the radiating area ($2\pi a_0^2$), we arrive at a characteristic temperature applicable to the fast-cooling limit (T. Piran et al. 2015; T. Ryu et al. 2020a):

$$\begin{aligned} T_{\text{peak}} &= \left(\frac{L_{\text{rad,peak}}}{2\pi a_0^2 (1 + 2h/r) \sigma_{\text{SB}}} \right)^{1/4} \\ &\simeq 3.9 \times 10^4 [(1 + 2h/r)(1 + t_{\text{cool}}/t_0)]^{-1/4} \\ &\quad \times \Xi^{9/8} m_{\text{BH},6}^{-3/8} \text{ K}. \end{aligned} \quad (19)$$

Just as it did for the luminosity, a shift of radial scale for the debris from $\sim r_p$ to $\sim a_0$ brings the temperature into the range actually observed (see Equation (9)). Thus, there is a strong prediction that the temperature is a few $\times 10^4 \text{ K}$, nearly independent of the star’s mass or whether the debris cools rapidly or slowly—and this is exactly the temperature generally observed. The principal parameter-dependence is on M_{BH} , which gives somewhat cooler temperatures for larger M_{BH} .

5.4.3. Duration

In the rapid-cooling regime, the optical/UV lightcurve should track the rate at which the debris’ internal energy would increase in the absence of cooling. This rate is driven by the mass-return rate, but its decline following the peak in the mass-return rate is more gradual, as fluid elements continue to

suffer shocks as they orbit around the black hole. Because the placement and strength of these shocks depend on details of the flow, the degree to which the decline is slower than the decline in the mass return rate could vary from case to case, which means a small set of simulations is insufficient to predict the specific shape of the declining lightcurve. Nonetheless, in this regime, the duration of the flare should generally be a few t_0 .

On the other hand, the peak luminosity of slowly cooling shocked debris (i.e., the debris in events for which $m_{\text{BH},6} \ll 0.3 [(f/0.15)(h/r)(\kappa/\kappa_T)]^{6/7} \Xi^{15/7} m_*^{0.4}$) is locked to its Eddington luminosity. Because, in addition, the total dissipated energy available for radiation varies extremely weakly with both M_{BH} and M_* , the optical/UV lightcurve for slowly cooling events should have a flat peak lasting $\simeq 0.5(h/r)(\kappa/\kappa_T) \Xi m_{\text{BH},6}^{-2/3} m_*^{0.78}$ months, followed by a decline once the thermal energy remaining can no longer support this luminosity. Note, however, that this limit usually applies when the black hole mass is small, making the duration typically a few months. Such a prediction was also made, for somewhat different reasons, in B. D. Metzger (2022).⁸

Thus, the relationship between the duration of the flare peak and t_0 is somewhat indirect. For rapidly cooling events, the period of high dissipation rate, and therefore maximum luminosity, lasts for $\sim t_0$ and then declines, perhaps $\propto t^{-5/3}$ and perhaps more slowly. For slowly cooling events, the Eddington-limited phase lasts for $\simeq 0.4 \Xi^{5/6} m_{\text{BH},6}^{-1/2} m_*^{0.47} (f/0.15)(h/r)(\kappa/\kappa_T) t_0$. For the smaller black holes associated with this limit, this phase has a duration $\gtrsim t_0$.

The brightest part of the flare ends once the system has cooled significantly. At this point, the accretion flow settles down to a geometrically thin eccentric disk with a size $\sim 10^3 r_g$ and an eccentricity ~ 0.5 . Further radiation during the time from $\sim 3t_0$ to $\sim 10t_0$ comes from tapping the remaining heat in the gas or the emergence of reprocessed light initially generated by promptly deflected matter. The latter may be significant because D. J. Price et al. (2024) found that hydrodynamic effects led to an accretion rate onto the black hole declining rather slowly, roughly $\propto t^{-0.7}$ out to $t \sim 9t_0$.

5.5. Scaling of Flare Properties with M_* and M_{BH}

In the previous subsections, we have shown how the placement of the debris mass at distances $\sim a_0$ leads to estimates of a variety of properties observable during the optical/UV flare. All of these estimates depend, to varying degrees, on M_* and M_{BH} . Part of the M_* and M_{BH} dependence is derived from traditional TDE order-of-magnitude Newtonian estimates, but part comes from the results of detailed simulations informed by main-sequence internal density profiles for the stars and general relativistic effects dependent on M_{BH} . Here we will describe how interesting observable properties depend on the stellar and black hole mass, incorporating both kinds of dependence and discuss how these relations can be inverted to infer M_* and M_{BH} from observations.

⁸ A number of the properties of this model overlap with ours: most of the bound debris residing on scales $\sim a_0$ for a long time, the large geometrical thickness of the flow, and, when $t_{\text{cool}} > t_0$, the roughly Eddington luminosity. The two models differ principally in that bulk kinetic energy and irregular elliptical gas flows are important in our model, but play no part in B. D. Metzger (2022).

5.5.1. Total Radiated Energy

The total energy dissipated during the flare $E_{\text{diss,peak}} \propto \Xi m_{\text{BH},6}^{1/3} m_{\star}^{0.78}$ (see Equation (11)). However, its actual scaling with $m_{\text{BH},6}$ is roughly $\propto m_{\text{BH},6}^{1/4}$ rather than $\propto m_{\text{BH},6}^{1/3}$ because Ξ declines with increasing $m_{\text{BH},6}$. On the other hand, Ξ increases with m_{\star} . Consequently, the total radiated optical/UV energy during the flare’s peak is a weakly rising function of M_{BH} , but rises somewhat more rapidly with M_{\star} .

5.5.2. Peak Optical/UV Luminosity

When cooling is rapid ($t_{\text{cool}} < t_0$), Equation (16) gives the stellar and black hole mass-dependence of the emitted luminosity: $\propto \Xi^{5/2} m_{\text{BH},6}^{-1/6} m_{\star}^{0.44}$. Although the explicit dependence of $L_{\text{rad,peak}}$ on $M_{\text{BH},6}$ is very weak, the implicit dependence through the $\Xi^{5/2}$ factor makes it a gradually declining function of black hole mass, roughly $\propto M_{\text{BH}}^{-3/8}$. On the other hand, the $\Xi^{5/2}$ factor significantly strengthens the increasing trend with M_{\star} , so that $L_{\text{rad,peak}} \propto M_{\star}^{1.8}$ and rises by a factor ~ 60 from $m_{\star} = 0.1$ to $m_{\star} = 3$. On the other hand, when cooling is slow, the peak luminosity is Eddington-limited, so $L_{\text{rad,peak}} \propto M_{\text{BH}}$ and is independent of M_{\star} .

5.5.3. Temperature

As already remarked, the observed temperature is extremely insensitive to either M_{\star} or M_{BH} . For rapidly cooling events, the temperature rises slightly with increasing M_{\star} through the function Ξ ’s dependence on the stellar mass, while it declines gradually ($\propto m_{\text{BH},6}^{-3/8}$) with increasing M_{BH} . The temperature of slowly cooling events depends extremely weakly on the masses: $\propto \Xi^{1/2} m_{\text{BH},6}^{-1/12} m_{\star}^{-0.11}$.

5.5.4. Duration

As discussed in Section 3.2 and originally pointed out in T. Ryu et al. (2020c; see Figure 8(a) therein), the increase of Ξ with M_{\star} causes t_0 to be almost independent of M_{\star} . For this reason, the timescale of a flare is a very weak indicator of M_{\star} . It is, on the other hand, $\propto M_{\text{BH}}^{0.6}$. Unfortunately, the persistence of shock heating for several t_0 means that the period of greatest luminosity is a few t_0 . Quantitative prediction of the flare duration therefore demands a better calibration of “a few” than the simulations to date can give.

5.5.5. Parameter Inference

Parameter inference is, of course, most precise when the data’s dependence on the parameter is strong. The assembled scalings above show that the only truly strong dependence is that of the peak luminosity on M_{\star} ($L_{\text{rad,peak}} \propto M_{\star}^{1.8}$) when the event is in the rapid-cooling regime.

Because the radiative efficiency of the debris shocks is much smaller than the canonical relativistic radiative efficiency, events of typical luminosity can be readily explained as associated with stars with $m_{\star} \sim 1$, rather than as very low-mass stars as has sometimes been suggested (B. Mockler & E. Ramirez-Ruiz 2021; M. Nicholl et al. 2022). In fact, because $L_{\text{rad,peak}} \propto m_{\star}^{1.8}$ when rapid-cooling applies, despite the larger numbers of low-mass stars, the frequency of low-mass star events in flux-limited samples should be rather low (see Section 5.8 and Figure 3).

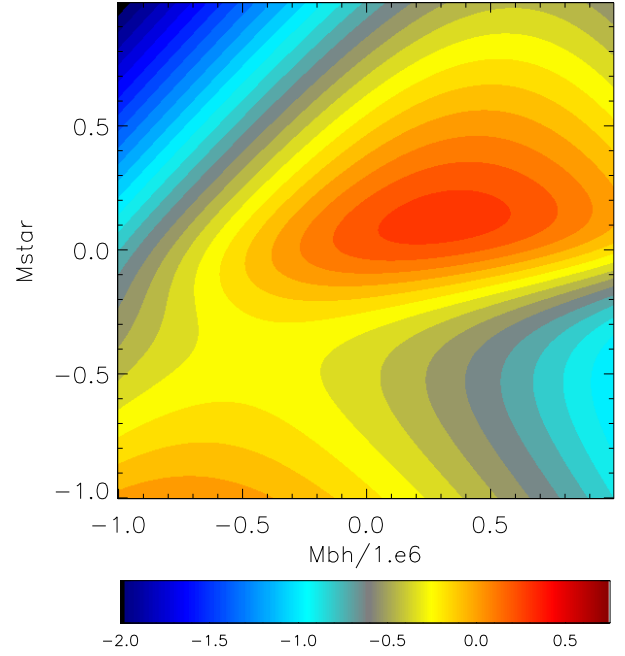


Figure 3. Logarithmic contours of relative event rates $\partial^2 \dot{N}_{\text{TDE}} / \partial \log M_{\text{BH}} \partial \log m_{\star}$ as found in flux-limited samples for a Salpeter mass function. The intrinsic event rate per star per galaxy is assumed to be independent of both the stellar and black hole mass. Both m_{\star} and $m_{\text{BH},6}$ are plotted logarithmically ranging from 0.1–10.

The next strongest dependence is the linear proportionality of $L_{\text{rad,peak}}$ to M_{BH} in the slow-cooling limit. Regrettably, because slow cooling applies for smaller M_{BH} , such events are harder to detect and less likely to appear in flux-limited samples.

In a previous paper on this topic (T. Ryu et al. 2020a), we presented a method (called TDEMASS) for using measurements of $L_{\text{rad,peak}}$ and T_{peak} to infer M_{\star} and M_{BH} . In that work, we did not include the effect of slow cooling, so we argued that $T_{\text{peak}} \propto m_{\text{BH},6}^{-3/8}$ for all cases; allowing for slow cooling drastically weakens that dependence so that the temperature in that limit is very nearly independent of M_{BH} .

To use this method on data, we have incorporated into the existing Python code implementing TDEMASS a new algorithm to solve Equation (17), rather than Equation (16); the code is available on github⁹ and Zenodo (T. Ryu 2025). We encourage interested readers to download an updated version incorporating slow-cooling effects.

5.6. Late-time Evolution

Over longer timescales, years or more, nearly all of the bound mass should eventually accrete. If most accretes with high radiative efficiency, the total energy emitted over long timescales could be as large as $\sim 10^{53} m_{\star}$ erg, several hundred times the energy emitted during the flare. Indeed, even observing TDEs for a few years past the flare has shown that the total energy radiated at late times, $\sim 3 \times 10^{50} \Xi^{3/2} (h/0.1r)^2 m_{\text{BH},6}^{-1/2} m_{\star}^{0.18} (\Delta t/1 \text{ yr})$ erg, is comparable to the total energy radiated during the flare. This fact, in itself, confirms what the three global simulations have shown: that the majority of the debris mass cannot have been brought to smaller radii during the flare, and that the inward progress of

⁹ <https://github.com/taehoryu/TDEmass.git>

the debris is generically very slow. This conclusion is contrary to the assumption made in many models that the matter is deposited at small radius ($r \sim r_p$) early on and then spreads both inward and outward (J. K. Cannizzo et al. 1990; R.-F. Shen & C. D. Matzner 2014; A. Mummery & S. A. Balbus 2020).

Much about late-time behavior is beyond what can be predicted from the three simulations' results. For example, whether the entire $\sim 10^{53} m_*$ erg is eventually radiated is unclear. Among numerous uncertainties, the radiated energy could be reduced to the extent that some of the gas acquires especially low angular momentum; such gas can plunge ballistically, passing through the event horizon without significant dissipation (G. Svirski et al. 2017).

On the other hand, certain properties of the late-time luminosity can be discerned from what we now know. One robust characteristic is that the inflow time is long because the mass is deposited far from the black hole. If inflow is driven by angular momentum transport, it requires internal stresses, which are generally due to correlated MHD turbulence. Building the turbulence from scratch takes ~ 5 – 10 orbital periods, i.e., ~ 5 – $10 t_0$, whether the orbits are circular or elliptical (J. M. Stone et al. 1996; J. F. Hawley & J. H. Krolik 2001; C.-H. Chan et al. 2024). Even after the turbulence reaches nonlinear saturation, there is considerable uncertainty about the magnitude of the resulting stresses. The inflow time is conventionally parameterized in terms of a pair of ratios, neither one easy to predict: $t_{\text{inflow}} \sim \alpha^{-1} (r/h)^2$ orbital periods, where α is the time-averaged and azimuthally averaged ratio of the vertically integrated stress to the vertically integrated pressure. Guessing at these parameters, one might expect (H. Shiokawa et al. 2015) that the timescale on which most of the debris accretes is $t_{\text{late}} \gtrsim 2 \times 10^3 (\alpha/0.1)^{-1} (h/0.1r)^{-2} t_0$. Here we scale h/r in terms of 0.1 because the inflow timescale is likely longer than the cooling time. In terms of TDE parameters, this expression for the inflow time translates to

$$t_{\text{late}} \sim 200 \Xi^{-3/2} (\alpha/0.1)^{-1} (h/0.1r)^{-2} m_{\text{BH},6}^{1/2} m_*^{0.82} \text{ yr}. \quad (20)$$

We emphasize that the fiducial quantities in this expression are plausible, but hardly well determined.

If, as one would expect, t_{late} is at least several years, it immediately follows that the luminosity radiated as the matter accretes toward the black hole should not have major trends on timescales shorter than several years. In other words, the late-time luminosity should flatten out. In fact, the lightcurves of many TDEs do just this at times ~ 1 yr past peak. When they do, the most common value of $L_{\text{late}}/L_{\text{rad,peak}}$ measured in terms of νL_ν in the near-UV (NUV) is ~ 0.1 , but in some cases, it is smaller by a factor of several to 10 (S. van Velzen et al. 2019b; Y. Yao et al. 2023; A. Mummery et al. 2024). That the luminosity remains within 1 or 2 orders of magnitude of the flare peak for many years can be readily understood. The radiative efficiency of matter accreting onto a black hole is $\sim 10^2 \times$ greater than the radiative efficiency of shocks on the $r \sim a_0$ scale, and this advantage comes close to compensating for the disadvantage of a timescale $\sim 10^3 \times$ longer.

Substantial scatter in the ratio of late-time to flare amplitude might be expected from a number of causes. The saturation amplitude of the MHD turbulence may depend on accretion conditions. With much of the debris remaining at distances $\gtrsim 10^3 r_g$ while the accretion luminosity is produced, as usual,

close to the black hole, some fraction of solid angle may be blocked by the debris. The debris orbits at large distance from the black hole should align with the stellar orbit, but Lense–Thirring torques acting closer to the black hole may modulate the inflow or lead to dissipation due to mechanisms other than damping of MHD turbulence. This list is undoubtedly incomplete.

5.7. Matter Deflected to Small Radii

5.7.1. Luminosity

As mentioned in Sections 4.2 and 4.3, a small amount of debris is deflected inward by the nozzle shock. By this means, $\lesssim 1\%$ of the debris can, in fact, quickly enter an accretion flow with a radial scale comparable to the stellar pericenter. The inflow time this close to the black hole should be much smaller than t_0 , even after allowing for the time necessary for the MHD turbulence to reach a saturated amplitude, because the orbital period is only $\sim (M_*/M_{\text{BH}})^{1/2} t_0 \sim 10^{-3} (m_*/m_{\text{BH},6})^{1/2} t_0$. As a result, the accretion rate through this small disk should be very close to the inward-deflection rate. At $t \sim 1$ – $3 t_0$, T. Ryu et al. (2023b) found the deflection rate to be $\dot{M}_{\text{defl}} \sim 0.01 M_*/t_0$, about twice the peak black hole accretion rate found by D. J. Price et al. (2024), $\sim 0.005 M_*/t_0$. If the radiative efficiency is relativistic, the associated luminosity could be as large as

$$L_{\text{defl}} \simeq 2.5 \times 10^{44} \left(\frac{\eta_{\text{rel}}}{0.1} \right) \left(\frac{\dot{M}_{\text{defl}}}{0.005 m_*/t_0} \right) \times \Xi^{3/2} m_{\text{BH},6}^{-1/2} m_*^{0.66} \text{ erg s}^{-1}. \quad (21)$$

Thus, the luminosity from the inner disk could be comparable to the luminosity from the shocked debris at much greater distance from the black hole; it would then also be mildly super-Eddington, particularly for smaller black holes and larger stars.

Taken at face value, L_{defl} declines with M_{BH} and increases with M_* , and the explicit mass-scalings for both are steepened by the trends in Ξ . However, there are numerous caveats and uncertainties attached to this estimate. The mass deflection rate itself remains poorly determined, and its dependence on m_* and $m_{\text{BH},6}$ is unknown. In addition, there are several ways the radiative efficiency of the deflected gas could be less than the canonical relativistic efficiency of 0.1. As mentioned briefly at the end of Section 4, the debris orbits have energy much greater than that of a circular orbit with their angular momentum. To join a small, circular orbit therefore requires the loss of a large amount of energy, and the simulations do not exhibit a mechanism for this. If the debris orbits lose a small amount of their angular momentum, the associated gas can plunge directly across the event horizon without having lost any of its kinetic energy to dissipation (G. Svirski et al. 2017). Even if the angular momentum of the deflected debris is large enough for it to go into orbit around the black hole, it may still be small enough that Reynolds stresses suffice to push the gas onto a plunging orbit; there may be associated dissipation, but too little time to radiate (C.-H. Chan et al. 2024). Even if there is dissipation and photons are emitted, high optical depth may suppress photon escape (D. J. Price et al. 2024) or reprocess the radiation, as we will discuss in the next subsection.

5.7.2. Spectrum

If the accreting matter close to the black hole during the flare period radiates a thermal spectrum, its temperature should be considerably higher than the light radiated by the bulk of the debris, but lower than if all the debris mass were promptly placed in such a small disk (see Equation (9)):

$$T_{\text{defl}} \approx \left(\frac{L_{\text{defl}}}{2\pi\sigma_{\text{SB}}(10r_g)^2} \right)^{1/4} \approx 7.5 \times 10^5 \left(\frac{\eta_{\text{rel}}}{0.1} \right)^{1/4} \times \left(\frac{\dot{M}_{\text{defl}}}{0.005\dot{m}_*} \right)^{1/4} \Xi^{5/8} m_{\text{BH},6}^{-5/8} m_*^{0.16} \text{ K} . \quad (22)$$

The characteristic energy is therefore $\sim 50\text{--}100$ eV, i.e., soft X-rays (J. Krolik et al. 2016); the systematic uncertainties expressed in the scaling factors for η_{rel} and \dot{M}_{defl} remain, but compressed by the 1/4 power relative to their influence on L_{defl} . Higher-mass black holes should tend to have softer X-ray spectra because, in addition to its explicit dependence on M_{BH} , T_{defl} also decreases with higher M_{BH} through $\Xi(M_{\text{BH}})$.

It is interesting to compare this prediction to the observed spectra of steadily accreting supermassive black holes, i.e., active galactic nuclei (AGNs). For the nonblazar varieties, the spectral band contributing the most to the bolometric luminosity is the far-UV (FUV; J. H. Krolik 1999). That thermal emission from the inner rings produces FUV rather than soft X-rays may be understood by writing the luminosity as a fraction \dot{m} of Eddington and supposing that it is radiated over the same area as used to estimate T_{defl} ; the result is $T_{\text{disk}} \simeq 7 \times 10^5 \dot{m}^{1/4} m_{\text{BH},6}^{-1/4}$ K. The lower disk temperatures in AGNs can then be explained by noting that the black hole masses in AGNs are often at least an order of magnitude (and sometimes several orders of magnitude) greater than $10^6 M_\odot$, and their Eddington-scaled accretion rates can be an order of magnitude below unity.

On the other hand, there is a stronger inconsistency with AGN X-ray spectra. In the typical case, the X-ray luminosity is $\sim O(10^{-1}) \times$ the bolometric luminosity, and takes the form of a fairly hard power law ($L_e \propto \epsilon^{-\alpha}$ with $0.5 \lesssim \alpha \lesssim 1$) with a high-energy cutoff at $\sim 50\text{--}200$ keV. Such power laws are only rarely seen in TDEs, and when they are, it is relatively late in the event (M. Guolo et al. 2024; S. Wen et al. 2024) or when jets are involved (J. S. Bloom et al. 2011; D. N. Burrows et al. 2011; A. J. Levan et al. 2011; S. B. Cenko et al. 2012). One might therefore speculate that higher \dot{m} suppresses hard X-ray emission, a thought that receives some support from simulation studies (B. E. Kinch et al. 2021) as well as observations made of $\sim 10 M_\odot$ black holes (R. A. Remillard & J. E. McClintock 2006).

When we see both the FUV and the coronal X-rays from AGNs, our line of sight to the central regions must be unobscured; the UV continuum from TDEs can be seen directly because it is generated on the outside of the debris. By contrast, soft X-rays from an inner disk in a TDE can suffer large amounts of obscuration by the surrounding debris. The optical depth of the main body of debris is quite large: as already estimated in Equation (13), electron scattering alone contributes an optical depth $\sim 300 \Xi^2 m_{\text{BH},6}^{-4/3} m_*^{0.55}$. If the gas's ionization balance is near LTE, atomic absorption processes like ionization of He^+ should significantly add to the opacity for photons with energy $\sim 50\text{--}200$ eV, while K-shell photoionization of C, N, and O creates substantial opacity for

photons with energy $\sim 200\text{--}1000$ eV. Closer to the black hole, where both the density and the temperature are higher, He^+ ionization contributes to the opacity wherever the temperature is $\lesssim 3 \times 10^5$ K. Consequently, soft X-rays radiated from near the black hole would be entirely absorbed if they pass through the bound debris (in agreement with E. Steinberg & N. C. Stone 2024, who found that, averaged over solid angle, the X-ray luminosity was only $\sim 10^{-2} \times$ the optical/UV luminosity).

Note that in this sense, reprocessing of photons radiated closer to the black hole can be important. However, it acts upon a far smaller luminosity than originally envisioned. This sort of reprocessing also contrasts with other reprocessing scenarios in that here the gas doing the reprocessing is the bulk of the bound debris, which remains at distances from the black hole $\sim 10^3 r_g$, rather than the debris made unbound at the time of disruption (L. E. Strubbe & E. Quataert 2009) or a wind driven by super-Eddington radiation (L. E. Strubbe & E. Quataert 2011; B. D. Metzger & N. C. Stone 2016).

In addition, whether the light is scattered or absorbed and reprocessed, the large optical depth also imposes a delay between when the initial photons are radiated and when they (or the photons into which their energy is transformed) reach the photosphere. Because, as we have already shown, the photon diffusion time through the outer regions of the flow can be significant compared to t_0 , the inner-region diffusion time can only make the total escape time longer.

Only within the small solid angle clear of obscuration would soft X-rays be observable at the time of the flare peak. However, their consequences may be observable from a much larger solid angle because they have energies large enough to photoionize a number of medium-Z elements to unusually high ionization states. Many of these ions have transitions linking their ground states to states only a few eV higher in energy, making the corresponding photons easily observable. The Bowen lines frequently, but not always, seen in TDEs (N. Blagorodnova et al. 2019; G. Leloudas et al. 2019; S. van Velzen et al. 2021) are examples: soft X-rays ionize He^+ ; recombination generates the $\text{He II Ly}\alpha$ line; these line photons are absorbed by near-resonances in N III and O III (species created by UV photons below the He II edge); collisional excitation generates optical/NUV lines from these ions. Because the gas has much lower absorption opacity in the optical/NUV, these emission lines can (absent obscuration farther out in the galaxy) be seen even when the X-ray photons are strongly obscured. Moreover, the lengthy diffusion time for these X-rays can create delays between the peak of the optical/UV flare and the appearance of the Bowen emission lines (P. Charalampopoulos et al. 2022); these delays may be augmented if the processes leading to X-ray radiation begin later than the shocks supplying the power for the optical/UV luminosity.

Depending on the ionization state of the debris gas near the edge of the optically thin cone, reflection from the Thomson-thick debris may enhance the X-ray flux seen by observers with lines of sight within the cone. Because of the several varieties of photoionization, the cone albedo is likely to have several ionization edges imprinted upon it. At later times, when the debris has cooled, the debris opening angle widens, making higher-energy photons from near the black hole visible to a larger fraction of distant observers. It is possible that by

the time this occurs, the spectrum of X-rays radiated near the black hole may be harder.

Somewhat fortuitously (because the dynamics and initial conditions are quite different), in respect to obscuration properties, the picture we have just described resembles qualitatively that put forward by L. Dai et al. (2018) and L. L. Thomsen et al. (2022). In the calculations reported in these papers, the gas density was assumed to be axisymmetric, to decline vertically so as to yield a constant aspect ratio $h/r = 0.3$, and to fall with increasing radius $\propto r^{-1.3}$ all the way to $r = 8500r_g$. The duration of the simulation, $20,000r_g/c \simeq 1.4 \times 10^{-6} \Xi^{3/2} m_{\text{BH},6}^{1/2} m_*^{-0.82} t_0$, was far too short for any evolution in the density at $r \gtrsim 50r_g$.¹⁰ Consequently, the majority of the debris mass was found at $r \gtrsim 3000r_g$ and had an aspect ratio only slightly smaller than the one arising in the global simulations. Thus, these papers' predictions having to do with obscuration during the flare peak are similar to ours.

5.8. Detected Event Rates

The considerations presented so far have interesting implications for the rate of observed TDEs. Almost every astronomical survey is, in some way, flux-limited. When the objects of interest exhibit a range of luminosities, this automatically entails a statistical bias for those with larger luminosity. If the sources have a uniform spatial density, the number of sources in the sample is proportional to the volume out to which the sources can be detected; for noncosmological extragalactic surveys (the case relevant to TDEs), the detected population is then $\propto L^{3/2}$. Because the peak luminosity for TDEs is, in the end, determined by where the debris is placed after returning to the black hole, even the relative rates of events involving different stellar and black hole masses are consequences of where the debris mass goes.

As we have seen in Figure 2, the range of predicted luminosities across the most likely portion of parameter space spans a factor $\sim 10^3$. The most-luminous events are therefore overrepresented relative to the least-luminous by a factor $\sim 3 \times 10^4$. The sense of this overrepresentation is to favor events with larger M_* and intermediate M_{BH} (as shown in Figure 2).

In the most naive model of the intrinsic TDE population, the probability of a TDE is independent of m_* , so that the number of events is proportional to the stellar mass function. Because the lifetimes of stars with $m_* \gtrsim 1$ are shorter than galaxy lifetimes, and higher-mass stars yield more luminous events, the rate of events with high luminosity is very sensitive to the proportion of stars formed comparatively recently among the stars near enough the black hole to be disruption candidates. At the other extreme, the rate of events with low luminosity is sensitive to the slope of the mass function at small m_* . Here we display in Figure 3 a simple example, a pure Salpeter mass function extending up to $10M_\odot$, and postpone more detailed discussions of event rates to another paper.

The shape of the detected events distribution in the $M_{\text{BH}} \times M_*$ plane reflects two trade-offs. In rough terms, the dependence on M_* balances the greater intrinsic number of low-mass stars against the higher luminosity of high- M_*

disruptions. The dependence on M_{BH} peaks at intermediate masses because events at lower black hole mass are limited to $\sim L_E \propto M_{\text{BH}}$ and events at higher mass have lower peak luminosities because the timescale is longer. In this example, using a Salpeter mass function, the luminosity bias places the highest event detection rate at $M_* \sim 1\text{--}1.5M_\odot$ and $M_{\text{BH}} \sim 1\text{--}3 \times 10^6 M_\odot$. The lowest rates are found at low stellar mass and high black hole mass ($M_* \lesssim 0.5M_\odot$ and $M_{\text{BH}} \gtrsim 6 \times 10^6 M_\odot$), and at high stellar mass and very low black hole mass: $M_* \gtrsim 5M_\odot$ and $M_{\text{BH}} \lesssim 2 \times 10^5 M_\odot$.

6. Summary

In the past year, three global TDE simulations in which events with astrophysically realistic parameters were studied ($M_* \sim 1M_\odot$ and $M_{\text{BH}} \sim 10^5\text{--}10^6 M_\odot$) have been published. Although they used different hydrodynamic algorithms (a fixed-grid intrinsically conservative method, a moving-mesh intrinsically conservative method, and SPH), in many respects, their results are very consistent. In particular, all three find that after a few characteristic orbital times for the debris, the overwhelming majority of the debris mass— $\gtrsim 99\%$ —is found at radii $\sim 3 \times 10^3 r_g$. Thus, this fact is now a robust prediction of the basic physics of these events, subject to alteration only for extreme parameter choices (e.g., stellar pericenters $\lesssim 10r_g$, for which strong apsidal precession would change the dynamics; J. Krolik et al. 2020).

Because the location of the mass directly implies many physical quantities: orbital binding energy, orbital timescale, photospheric area, etc., the robust agreement on where the mass goes leads to a similarly robust agreement in their predictions of important observable properties. Although in all three simulations the specific parameters chosen were selected only for being within the plausible range and for computational convenience, the simulations' predictions for the principal observables associated with the optical/UV flare lie squarely in the middle of the observed distribution (as compiled, e.g., by E. Hammerstein et al. 2023a; Y. Yao et al. 2023): total energy radiated a few $\times 10^{50}$ erg, peak optical/UV luminosity $\sim 1 \times 10^{44}$ erg s⁻¹, and temperature of a blackbody component $\simeq 3 \times 10^4$ K. This agreement with observed properties is especially striking because it is achieved entirely on the basis of physical calculations without any adjustment of parameters.

Note, however, that our model may not be applicable to events in which $M_{\text{BH}} \gtrsim 10^7 M_\odot$ because in this black hole mass range, the critical pericenter for a full disruption is $< 10r_g$, a regime in which apsidal precession is strong enough to alter the flow pattern found in the three simulations. In these cases, mass returns faster to the vicinity of the black hole, and we speculate that this is why a small number of events have $L_{\text{rad,peak}} \gtrsim 10^{45}$ erg s⁻¹.

In addition, the fact that nearly all of the mass is deposited at such a large distance from the black hole directly implies that its subsequent accretion will stretch over a long period of time. It immediately follows that after the flare, the luminosity should decline over a period of several times the characteristic debris orbital timescale until it flattens out and maintains a roughly constant luminosity for many years. This prediction, too, is only weakly dependent on parameters and is nonetheless in excellent agreement with observations. In fact, because the total energy radiated on several-year timescales is generically comparable to the energy radiated during the flare

¹⁰ Even though they assumed the debris contained far more magnetic flux than a star might have held, the inflow time at these radii was still far longer than the duration of their simulation.

(S. van Velzen et al. 2019a), observations demand a situation in which accretion of a large part of the debris mass takes place slowly.

All three simulations predict similar luminosities because the underlying mechanism is also similar: shocks dissipating $\sim 10^{-3}$ of the debris’ rest-mass energy on a timescale $\sim t_0$. For this reason, all three likewise share a scaling relationship for how the luminosity depends on M_* and M_{BH} . Because the accessible volume for flux-limited surveys is $\propto L^{3/2}$, the rate at which events are detected in such surveys is $\propto L(M_*, M_{\text{BH}})^{3/2} \partial^2 N_{\text{TDE}} / \partial M_* \partial M_{\text{BH}}$. Thus, the results of these simulations predict how much events with specific pairs of M_* and M_{BH} are favored (or disfavored) for appearance in surveys, relative to their true rate; the highest luminosities are always strongly overrepresented; events with $10\times$ the typical luminosity are overrepresented by a factor ~ 30 . Interestingly, the number of events with a given stellar mass peaks at $\sim 1M_\odot$ due to the trade-off between the larger numbers of lower-mass stars and the greater luminosity associated with higher-mass stars. The rate per $\log M_{\text{BH}}$ has a broad peak at $\sim 1-2 \times 10^6 M_\odot$, but the rate is at least half the peak value from $\sim 2 \times 10^5 M_\odot$ to $\sim 1 \times 10^7 M_\odot$. In agreement with this prediction, all of the independent estimates of black hole masses in the sample of T. Ryu et al. (2020a) are in this range, as are 28 of the 33 independently estimated black hole masses in the Y. Yao et al. (2023) compilation. Moreover, the Y. Yao et al. (2023) black hole mass distribution is consistent with being flat from $\sim 3 \times 10^5 M_\odot$ to $\sim 1 \times 10^7 M_\odot$.

All three simulations also agree that the fraction of the debris pushed quickly to radii within the stellar pericenter is $\lesssim 1\%$. Even though this is a very small fraction, it may possibly contribute to the bolometric luminosity of the flare at a level comparable to the bulk of the debris; its orbital binding energy is $\sim O(10^2)\times$ that of the bulk. This material may be the source of the soft X-rays sometimes seen in TDEs, and reprocessing of these soft X-rays at larger distances by the bulk of the debris may lead to the Bowen emission lines often seen. However, none of the simulations done so far have treated the inner region with sufficient care to determine either its immediate radiation properties or, at a quantitative level, how much obscuration and reprocessing the emitted light may suffer en route to distant observers.

Thus, the basic mechanics of the most common variety of events is now understood. Over timescales of a few t_0 , very nearly all of the debris retains its original orbital energy to within a factor $\sim O(1)$; in so doing, it remains a distance $\sim a_0$ from the black hole. The optical/UV flare results from radiating the energy that is dissipated. This matter approaches closer to the black hole only over much longer (years +) timescales. A small fraction ($\lesssim 1\%$) of the mass moves inward more rapidly. It should also be emphasized, however, that rarer varieties of TDEs—those with pericenters small enough to create large apsidal precession (e.g., T. Ryu et al. 2023a), or large enough to produce a partial disruption (e.g., T. Ryu et al. 2020e; C. Liu et al. 2025; M. Sharma et al. 2024), or those in which a massive disk already orbits the black hole (C.-H. Chan et al. 2019, 2021, 2022; B. McKernan et al. 2022; T. Ryu et al. 2024), for example—may behave differently.

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Appendix A

Stellar Structure and Relativistic Correction Factors

Two correction factors are important in estimating the dependence of observational properties on the stellar and the black hole masses. The first factor determines the relation between the real tidal radius \mathcal{R}_T and the order-of-magnitude estimate r_t : $\mathcal{R}_T = \Psi(M_*, M_{\text{BH}}) r_t$ (T. Ryu et al. 2020c, 2020d).

$$\Psi(m_*, m_{\text{BH},6}) = [0.80 + 0.26 m_{\text{BH},6}^{0.5}] \times \frac{1.47 + \exp[(m_* - 0.669)/0.137]}{1 + 2.34 \exp[(m_* - 0.669)/0.137]} \quad (\text{A1})$$

Ψ is a function of m_* , and possibly the star’s age and chemical composition, through the dependence of the star’s internal density profile on these factors. Taken as a function of m_* alone, it declines smoothly from ≈ 1.5 for very small m_* to ≈ 0.43 for all $m_* \gtrsim 1$. For a typical MS star encountering a black hole with $M_{\text{BH}} = 10^6 M_\odot$, $\mathcal{R}_T \approx 25 r_g$ almost independent of the stellar mass (J. A. P. Law-Smith et al. 2020; T. Ryu et al. 2020c, 2020d). This “physical tidal radius” is also a function of M_{BH} through the impact of general relativistic corrections; with r_t several tens of gravitational radii, they can be substantial (T. Ryu et al. 2020b, 2020c): the portion of Ψ dependent upon M_{BH} grows from ≈ 1.8 for $m_{\text{BH},6} \approx 10$ to ≈ 5 for $m_{\text{BH},6} = 100$.

The second correction factor $\Xi(M_*, M_{\text{BH}})$ defines the change in energy of the debris, ΔE , relative to the fiducial change ΔE_0 :

$$\Xi(m_*, m_{\text{BH},6}) \equiv [1.27 - 0.3 m_{\text{BH},6}^{0.242}] \times \frac{0.62 + \exp[(m_* - 0.67)/0.21]}{1 + 0.55 \exp[(m_* - 0.67)/0.21]} \quad (\text{A2})$$

Like the factor Ψ , Ξ is a function of stellar mass, with additional possible dependence on stellar age and chemical composition. The function $\Xi(m_*)$ is almost opposite in behavior to $\Psi(m_*)$: Ξ rises from an asymptote ≈ 0.66 for $m_* \lesssim 0.3 M_\odot$ to an asymptote at ≈ 1.8 for $m_* \gtrsim 1.3 M_\odot$. Ξ also depends upon M_{BH} , particularly when $m_{\text{BH},6} \gtrsim 1$, because of general relativistic effects (T. Ryu et al. 2020b, 2020c): as a function of M_{BH} , Ξ falls from ≈ 1.3 in the Newtonian limit to ≈ 0.75 when $m_{\text{BH},6} = 10$ and to ≈ 0.3 at $m_{\text{BH},6} = 30$, beyond which the fitting formula no longer applies. Figure 4 illustrates how Ξ is greatest for large m_* and small $m_{\text{BH},6}$ and least for small m_* and large $m_{\text{BH},6}$.

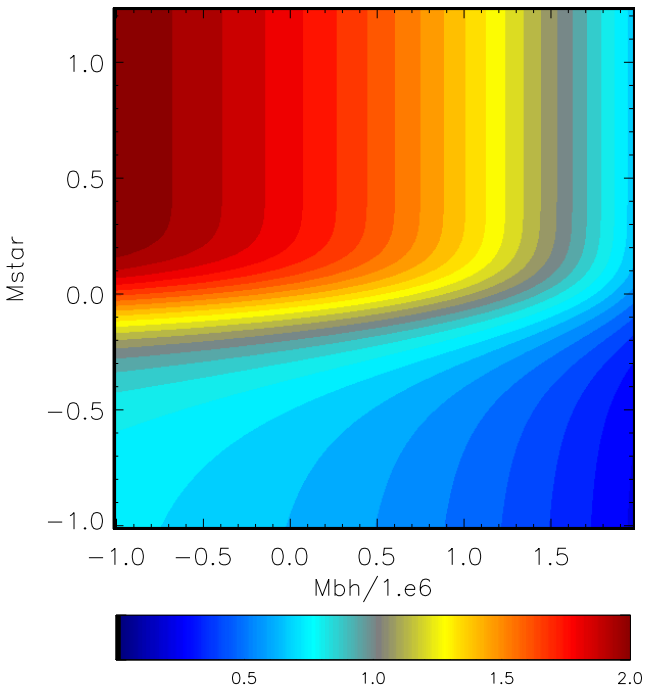


Figure 4. Linear color contours of $\Xi(m_*, m_{\text{BH},6})$ as a function of the logarithms of m_* and $m_{\text{BH},6}$.

Appendix B The Eddington Luminosity Limit

That the luminosity is limited to approximately Eddington is, in fact, a general result when a gas is heated to nearly the virial temperature (in the sense of associated photon energy density per unit mass), and is then left to radiatively cool in an environment whose opacity is $\sim \kappa_T$ (J. H. Krolik 2010; C.-H. Chan et al. 2020). This may be seen from a very simple argument. If $U_{\text{rad}}/\rho \sim GM/r$ in a homogeneous sphere, the luminosity is roughly

$$L \sim \frac{GMM_g}{r} (c/r) [1 + 3\kappa_T M_g / (4\pi r^2)]^{-1}, \quad (\text{B1})$$

where M is the central mass and r is radius of the sphere. The optical depth $\tau_T(r) \sim (3/4\pi)\kappa_T M_g / r^2$. Using the definition $L_E = 4\pi cGM/\kappa_T$, this approximation to the luminosity becomes

$$L \sim \frac{L_E}{3(1 + 1/\tau_T(r))}. \quad (\text{B2})$$

Thus, the luminosity is $\sim L_E \tau_T$ when $\tau_T < 1$ and rises to $\sim L_E$ when $\tau_T > 1$.

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